



Universität Hamburg

DER FORSCHUNG | DER LEHRE | DER BILDUNG

MIN Faculty  
Department of Informatics



# Integration of Conductive Materials and SMD-Components into the FDM Printing Process for Direct Embedding of Electronic Circuits

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PhD Thesis Defense

University of Hamburg  
TAMS

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# Fused Deposition Modeling (FDM)

Introduction

Hardware

Related Work

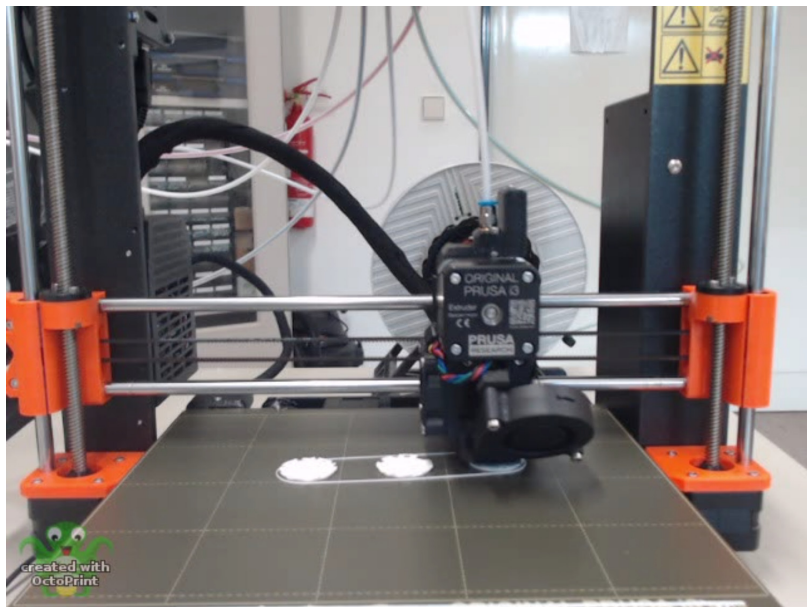
CAD / CAM Software

Routing

Inspection

Evaluation

Conclusion



# Motivation

Introduction

Hardware

Related Work

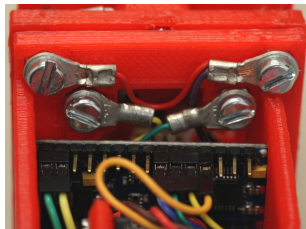
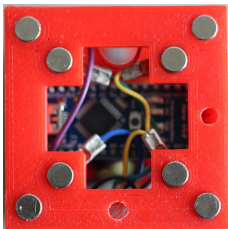
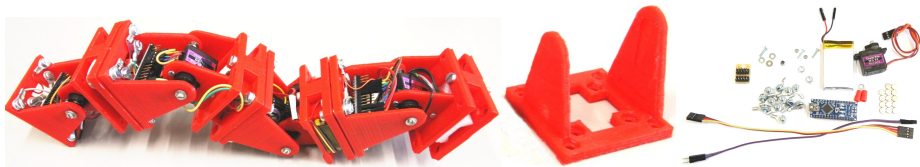
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# Mission Statement

Full integration of electronic components and circuits into plastic objects in a single additive manufacturing process.



# Mission Statement

Full integration of electronic components and circuits into plastic objects in a single additive manufacturing process.

+ Keep it low-cost!

# Challenges

1. Hardware / Materials
2. Design (CAD) and Routing Software
3. Machine Control and Calibration
4. Documentation and Inspection

## Hardware

[1]: Florens Wasserfall. Embedding of SMD populated circuits into FDM printed objects. In *Proceedings of the 26th International Solid Freeform Fabrication Symposium*, pages 180–189, 2015

# Materials

Introduction

Hardware

Related Work

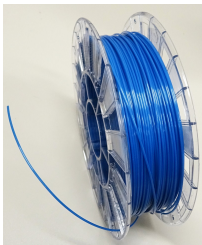
CAD / CAM Software

Routing

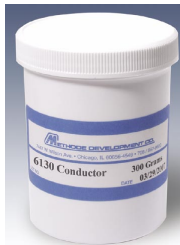
Inspection

Evaluation

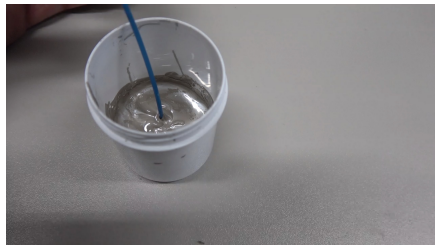
Conclusion



Filament



Silver Ink



Ink Processing

# Developing the Hardware

Introduction

Hardware

Related Work

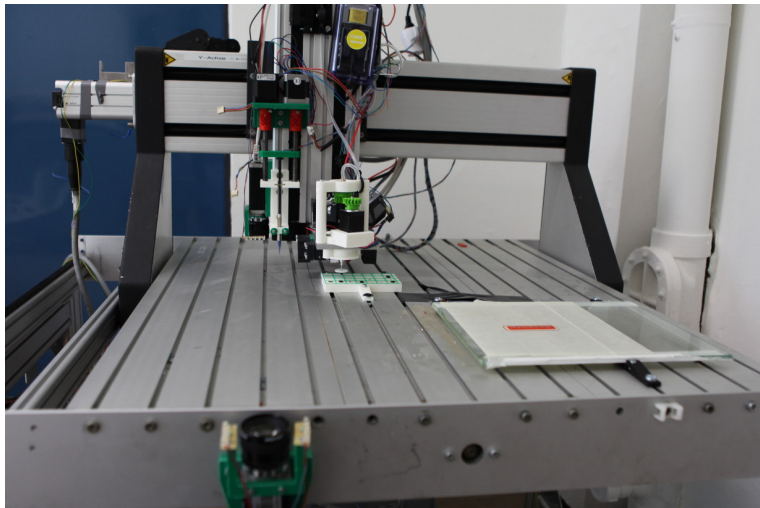
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Routing

Inspection

Evaluation

Conclusion



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Introduction

Hardware

Related Work

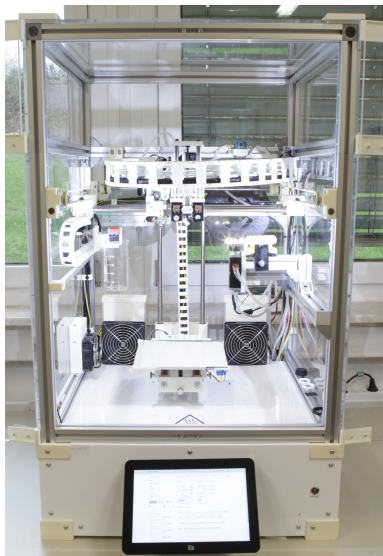
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Routing

Inspection

Evaluation

Conclusion



# Developing the Hardware

Introduction

Hardware

Related Work

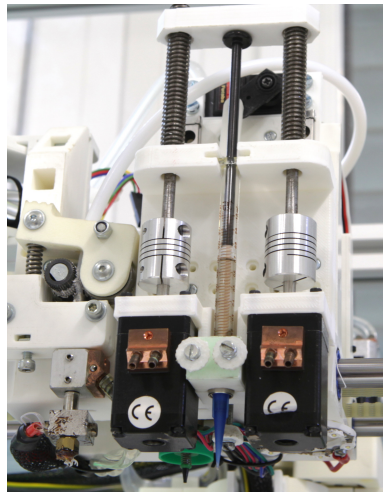
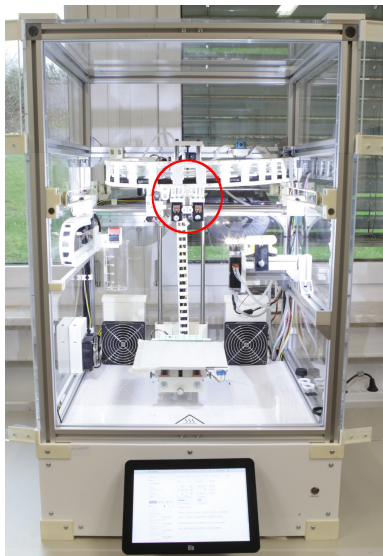
CAD / CAM Software

Routing

Inspection

Evaluation

Conclusion



Conductive ink extruder

# Developing the Hardware

Introduction

Hardware

Related Work

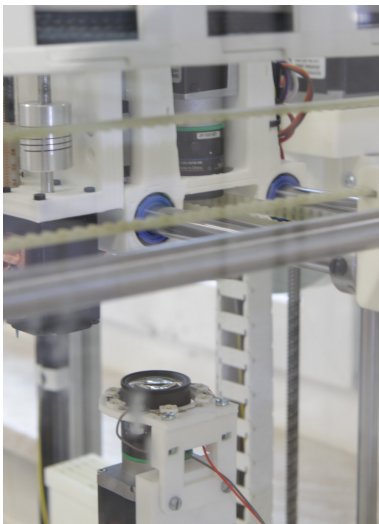
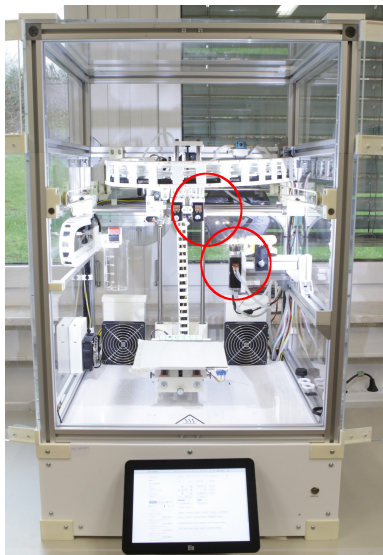
CAD / CAM Software

Routing

Inspection

Evaluation

Conclusion



Cameras



# Developing the Hardware

Introduction

Hardware

Related Work

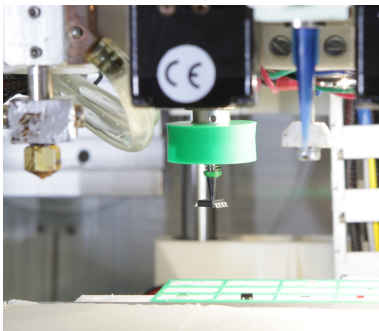
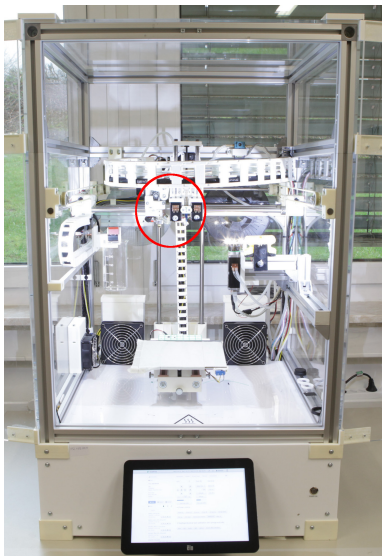
CAD / CAM Software

Routing

Inspection

Evaluation

Conclusion



Vacuum gripper

# Developing the Hardware

Introduction

Hardware

Related Work

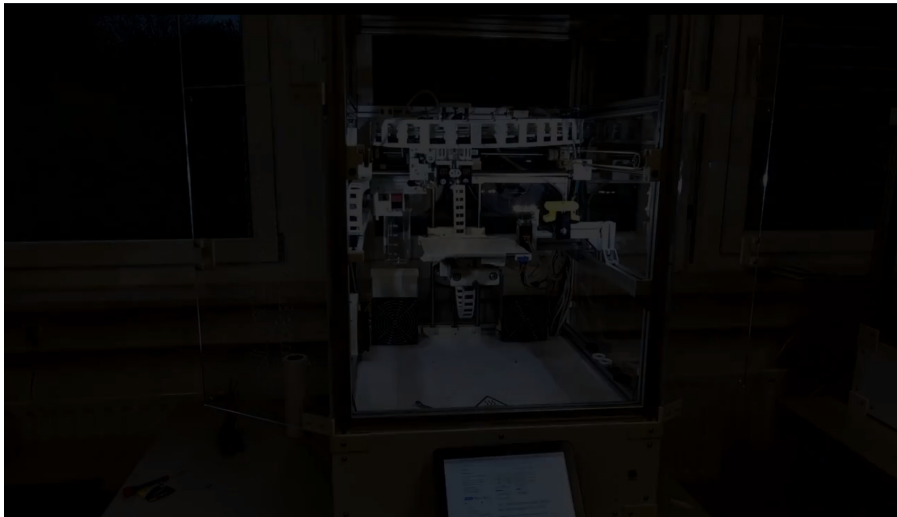
CAD / CAM Software

Routing

Inspection

Evaluation

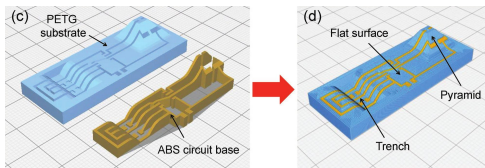
Conclusion



## Related Work

# Current approaches

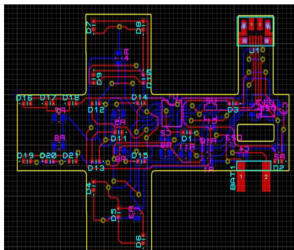
- ▶ Hand crafted CAD design
- ▶ Folding / mapping of PCB layouts
- ▶ Autodesk Project Wire
- ▶ Augmented CAM Processors
- ▶ Nextra / Target 3001!



[Ji Li et al. *Hybrid Additive Manufacturing Method for Selective Plating of Freeform Circuitry on 3D Printed Plastic Structure*, 2019]

# Current approaches

- ▶ Hand crafted CAD design
- ▶ Folding / mapping of PCB layouts
- ▶ Autodesk Project Wire
- ▶ Augmented CAM Processors
- ▶ Nextra / Target 3001!



# Current approaches

Introduction

Hardware

Related Work

CAD / CAM Software

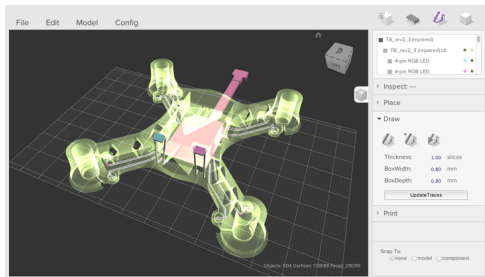
Routing

Inspection

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Conclusion

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[Autodesk]

# Current approaches

Introduction

Hardware

Related Work

CAD / CAM Software

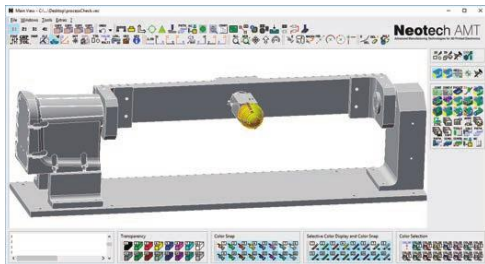
Routing

Inspection

Evaluation

Conclusion

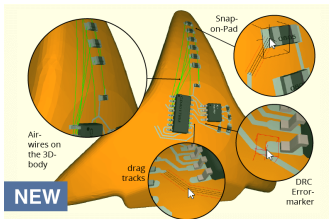
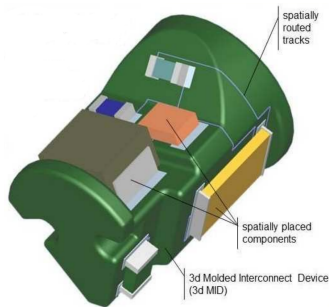
- ▶ Hand crafted CAD design
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- ▶ Nextra / Target 3001!



[Ankenbrand et al. *Mechatronic Integrated Devices*, 2019]

# Current approaches

- ▶ Hand crafted CAD design
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- ▶ Autodesk Project Wire
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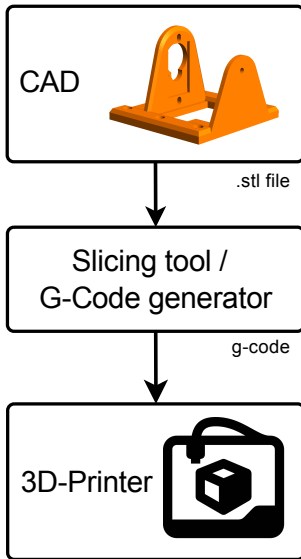


## CAD / CAM Software

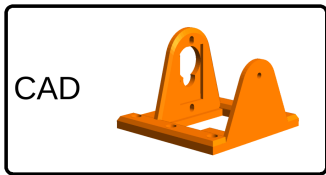
[2]: Florens Wasserfall, Daniel Ahlers, Norman Hendrich, and Jianwei Zhang.

3D-Printable Electronics - Integration of SMD Placement and Wiring into the Slicing Process for FDM Fabrication. In *Proceedings of the 27th International Solid Freeform Fabrication Symposium*, pages 1826–1837, Austin, 2016

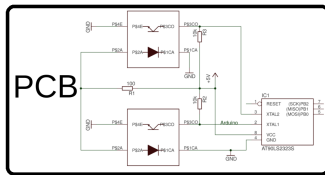
# Software Tool-Chain



# Software Tool-Chain



.stl file



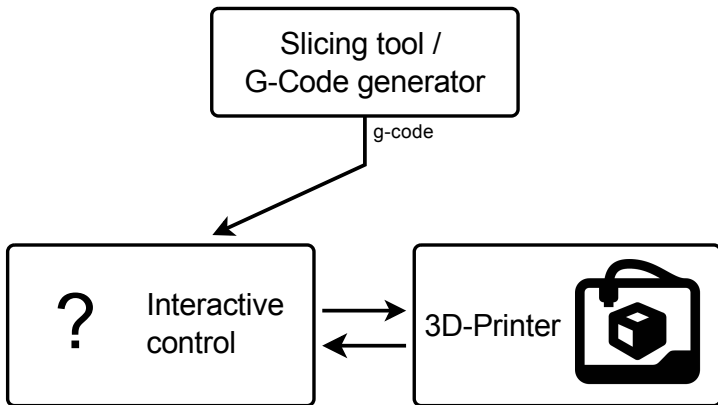
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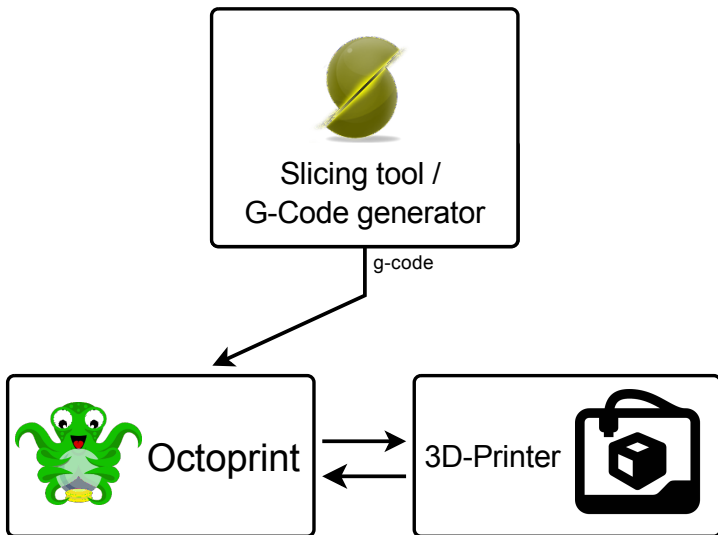
Slicing tool /  
G-Code generator

g-code

# Software Tool-Chain



# Software Tool-Chain



# Software User Interface

Introduction

Hardware

Related Work

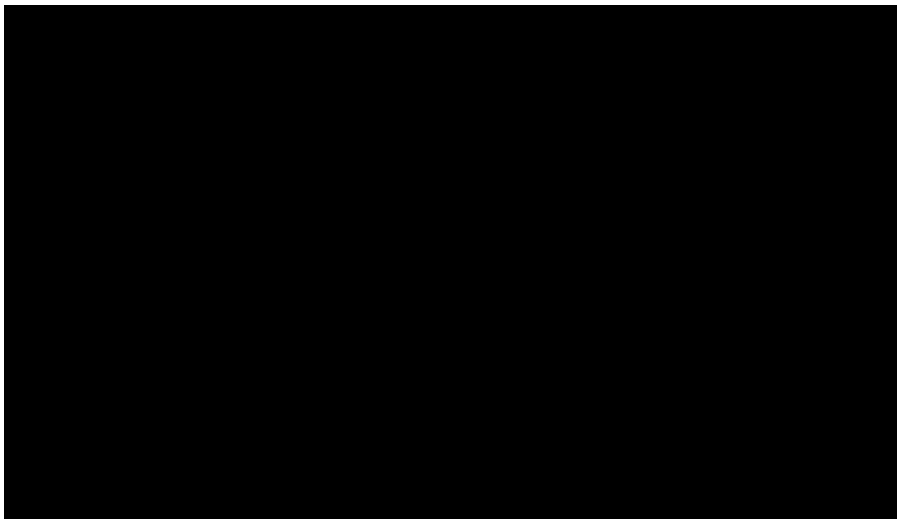
CAD / CAM Software

Routing

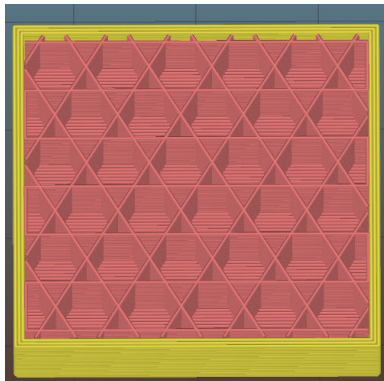
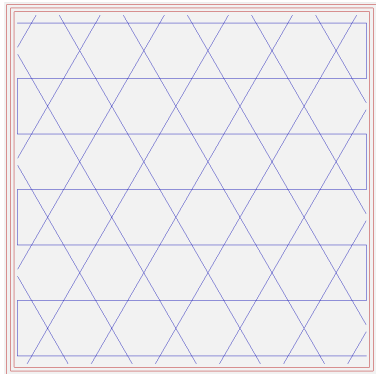
Inspection

Evaluation

Conclusion



# Wire generation



# Wire generation

Introduction

Hardware

Related Work

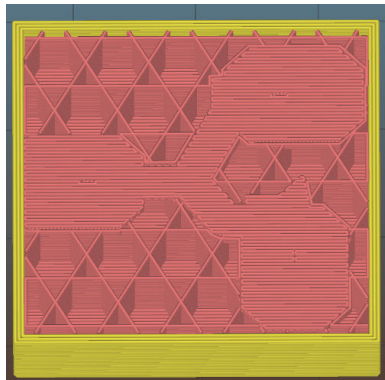
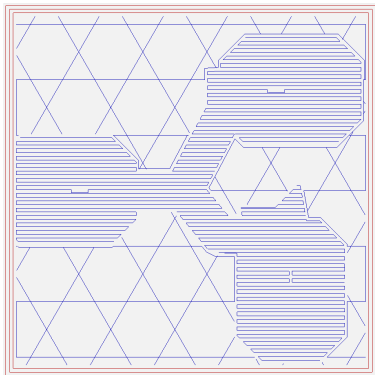
CAD / CAM Software

Routing

Inspection

Evaluation

Conclusion





# Wire generation

Introduction

Hardware

Related Work

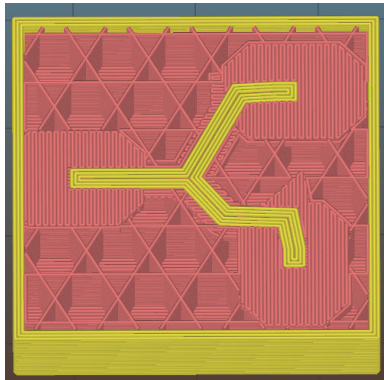
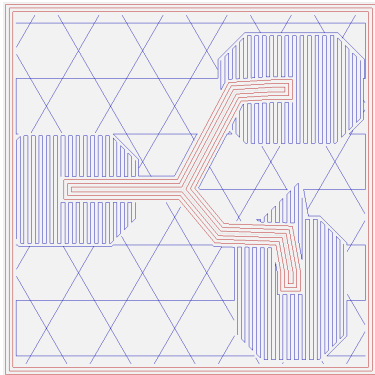
CAD / CAM Software

Routing

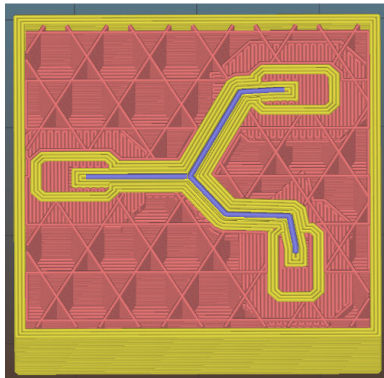
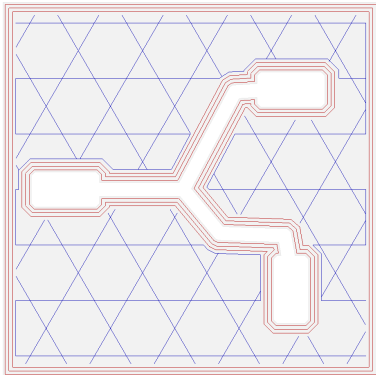
Inspection

Evaluation

Conclusion



# Wire generation



# Wire generation

Introduction

Hardware

Related Work

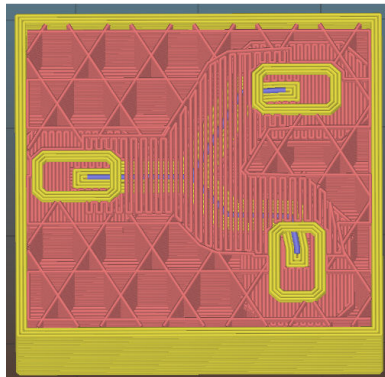
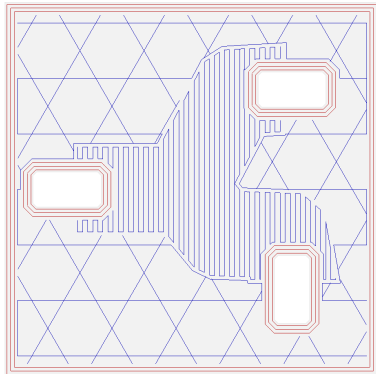
CAD / CAM Software

Routing

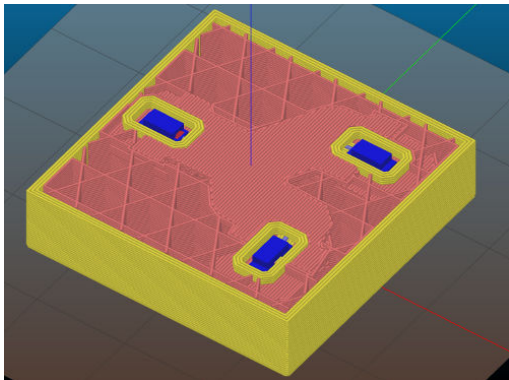
Inspection

Evaluation

Conclusion



# Wire generation



# Wire generation

Introduction

Hardware

Related Work

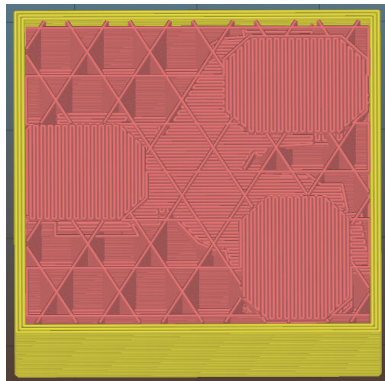
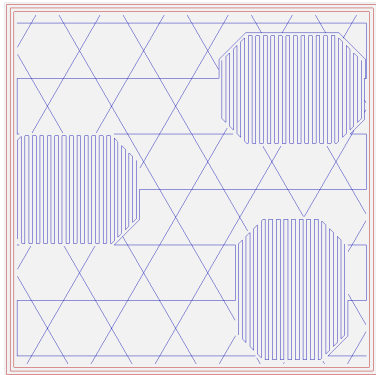
CAD / CAM Software

Routing

Inspection

Evaluation

Conclusion



## Routing

[3]: Florens Wasserfall. Topology-Aware Routing of Electric Wires in FDM-Printed Objects. In *Proceedings of the 29th International Solid Freeform Fabrication Symposium*, pages 1649–1659, Austin, 2018

# Planar Routing

Introduction

Hardware

Related Work

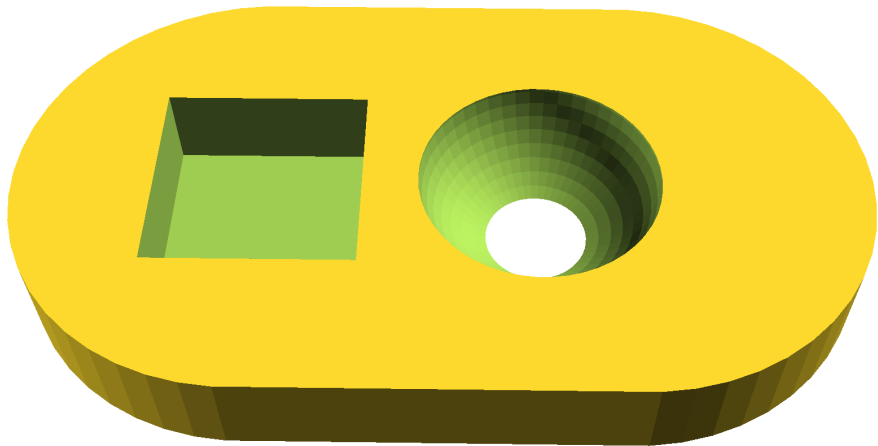
CAD / CAM Software

**Routing**

Inspection

Evaluation

Conclusion



# Planar Routing

Introduction

Hardware

Related Work

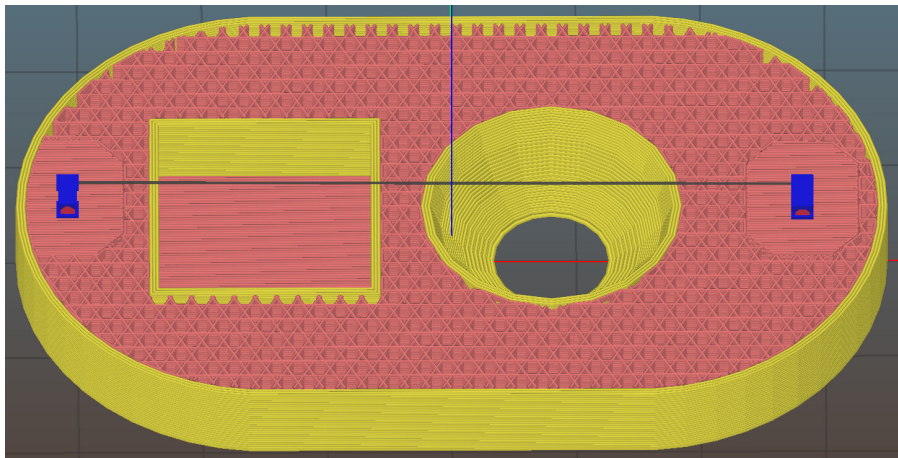
CAD / CAM Software

**Routing**

Inspection

Evaluation

Conclusion





# Planar Routing

Introduction

Hardware

Related Work

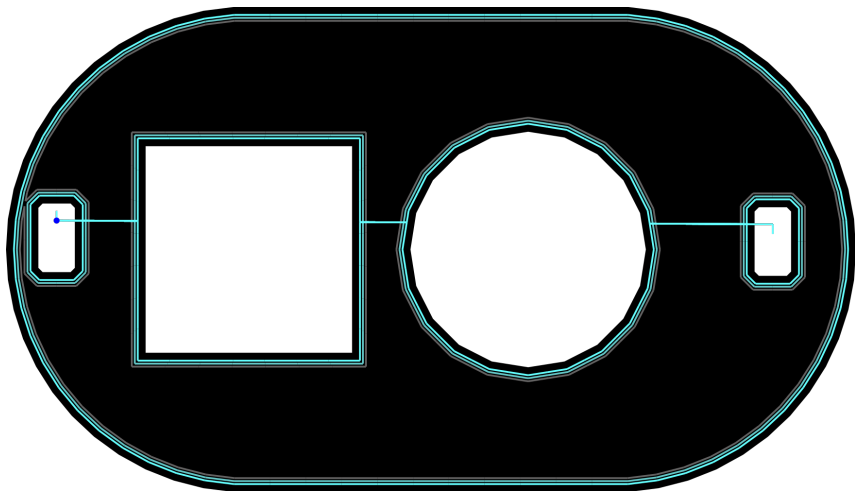
CAD / CAM Software

**Routing**

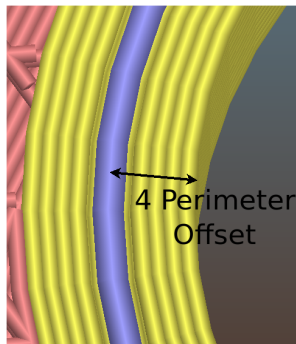
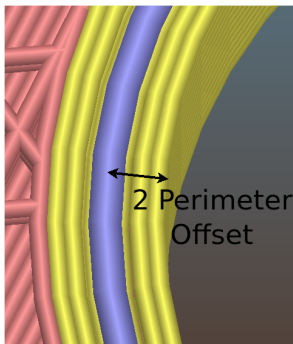
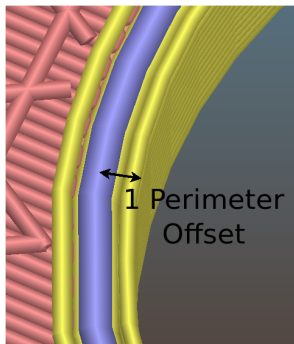
Inspection

Evaluation

Conclusion



# Planar Routing



# Planar Routing

Introduction

Hardware

Related Work

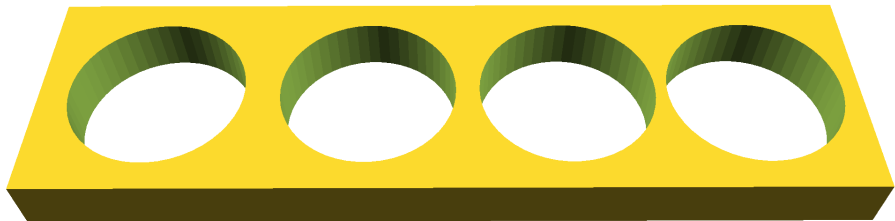
CAD / CAM Software

**Routing**

Inspection

Evaluation

Conclusion



# Planar Routing

Introduction

Hardware

Related Work

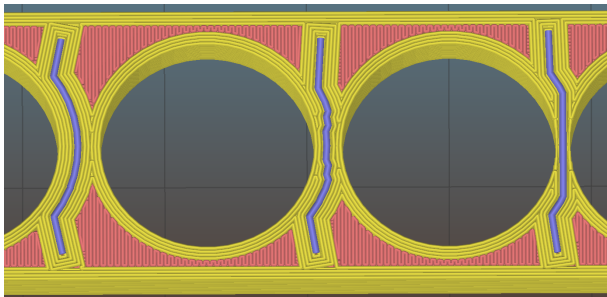
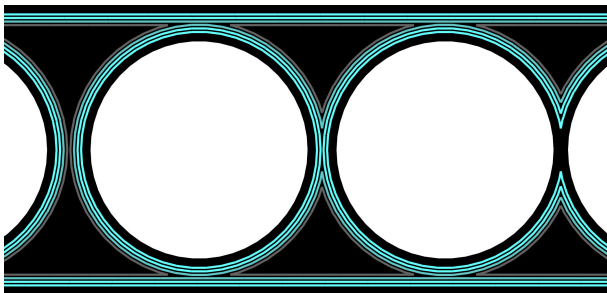
CAD / CAM Software

**Routing**

Inspection

Evaluation

Conclusion



# Planar Routing

Introduction

Hardware

Related Work

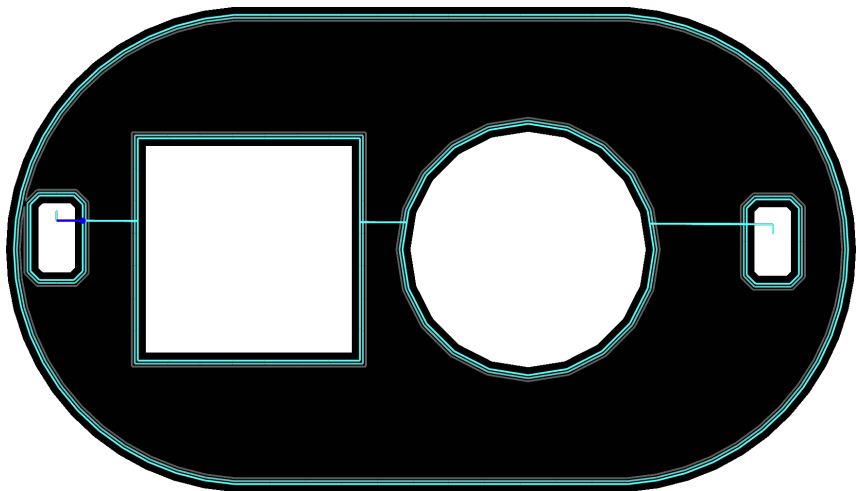
CAD / CAM Software

**Routing**

Inspection

Evaluation

Conclusion



# Planar Routing

Introduction

Hardware

Related Work

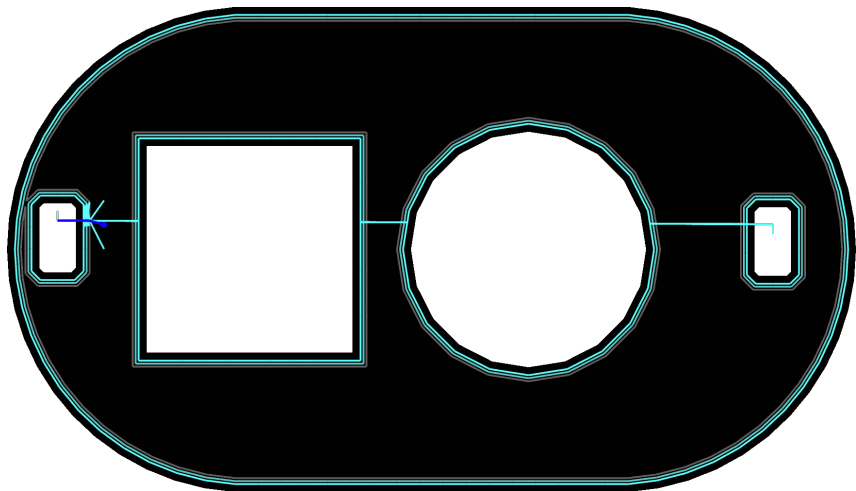
CAD / CAM Software

**Routing**

Inspection

Evaluation

Conclusion



# Planar Routing

Introduction

Hardware

Related Work

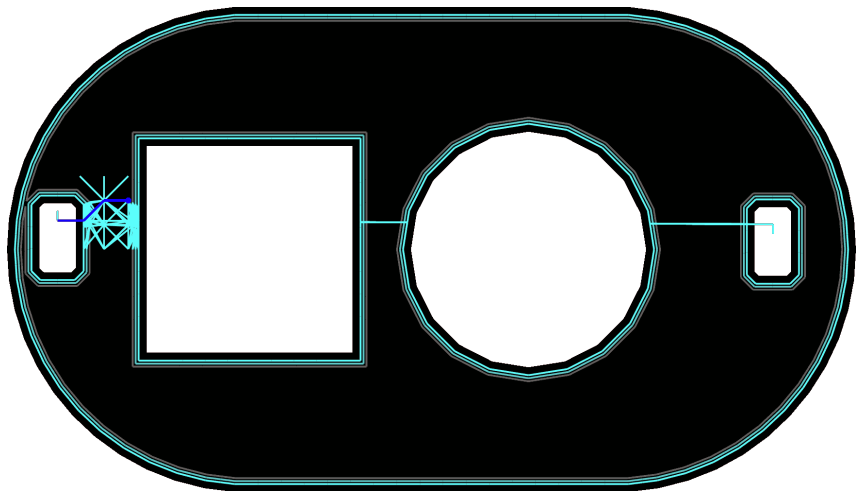
CAD / CAM Software

**Routing**

Inspection

Evaluation

Conclusion



# Planar Routing

Introduction

Hardware

Related Work

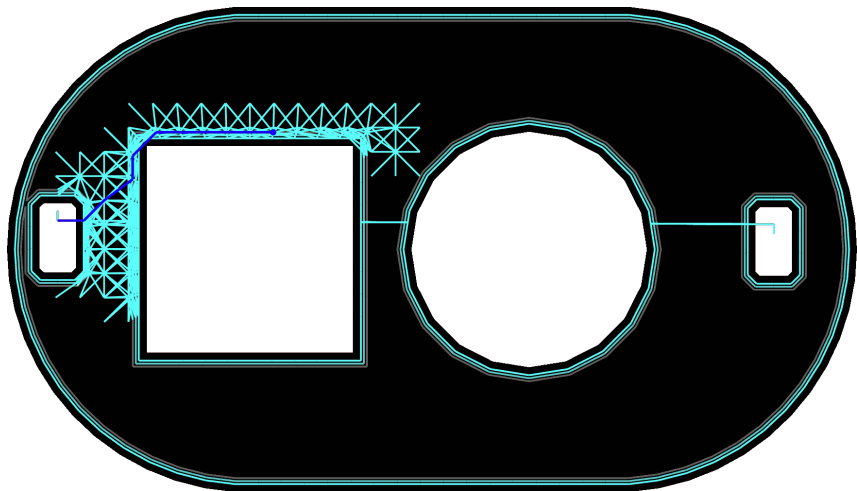
CAD / CAM Software

**Routing**

Inspection

Evaluation

Conclusion





# Planar Routing

Introduction

Hardware

Related Work

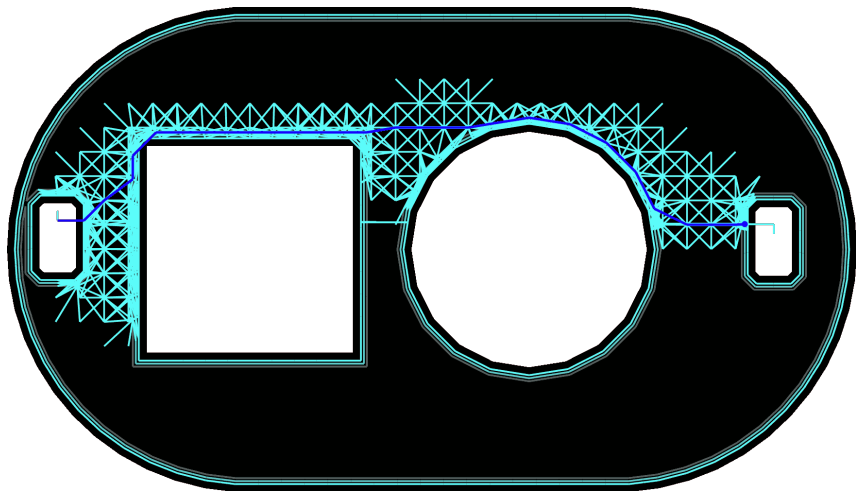
CAD / CAM Software

**Routing**

Inspection

Evaluation

Conclusion



# Planar Routing

Introduction

Hardware

Related Work

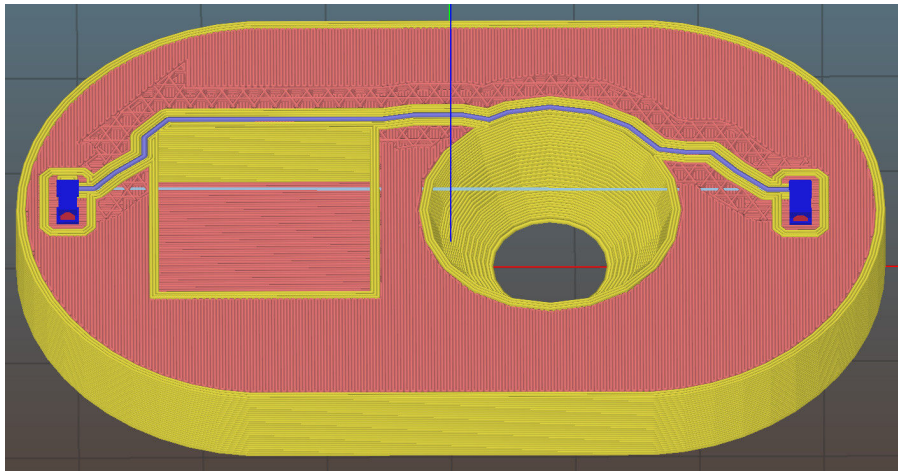
CAD / CAM Software

**Routing**

Inspection

Evaluation

Conclusion



# Planar Routing

Introduction

Hardware

Related Work

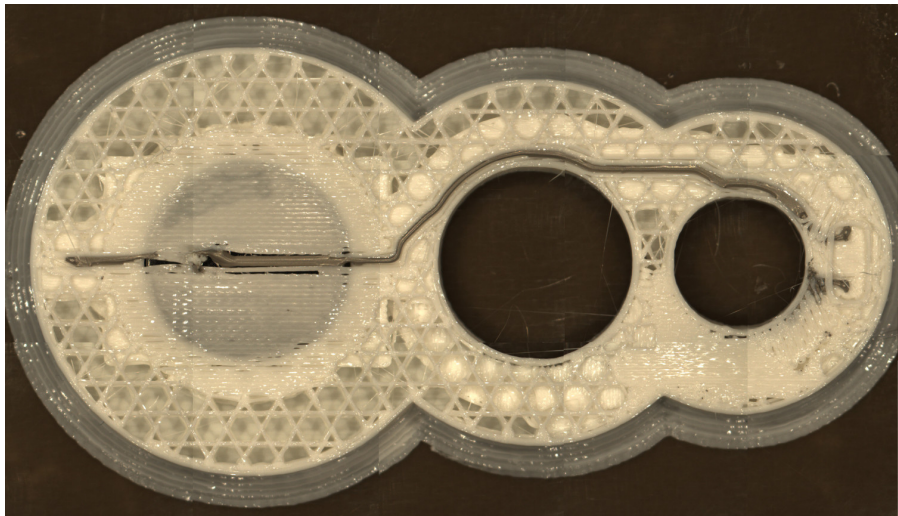
CAD / CAM Software

**Routing**

Inspection

Evaluation

Conclusion



# 3D Routing

Introduction

Hardware

Related Work

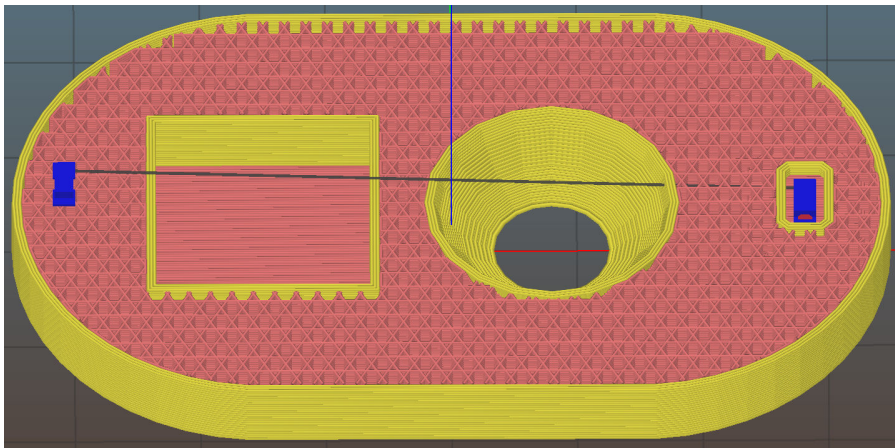
CAD / CAM Software

**Routing**

Inspection

Evaluation

Conclusion



# 3D Routing

Introduction

Hardware

Related Work

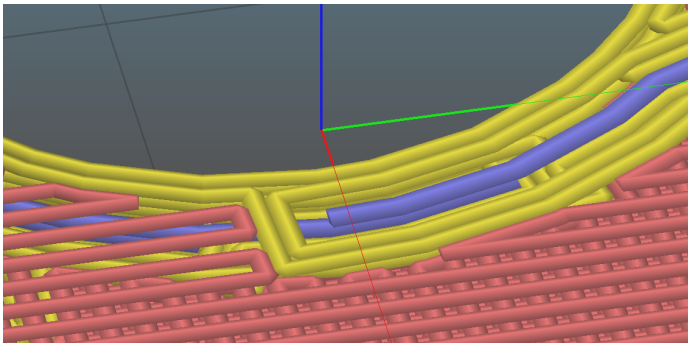
CAD / CAM Software

**Routing**

Inspection

Evaluation

Conclusion





# 3D Routing

Introduction

Hardware

Related Work

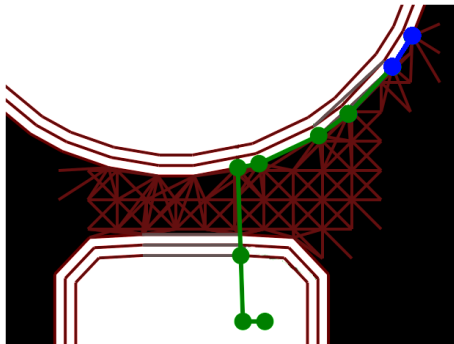
CAD / CAM Software

**Routing**

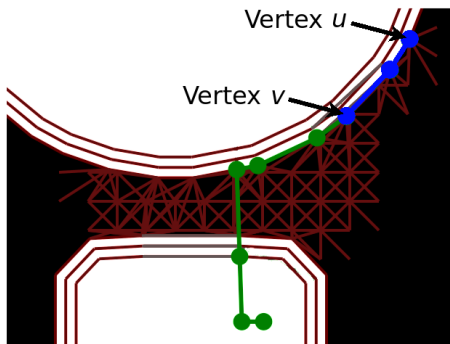
Inspection

Evaluation

Conclusion



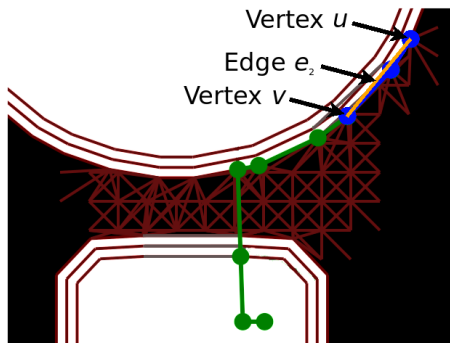
# 3D Routing



- ▶ overlap = 2mm
- ▶ grid\_step\_distance  $\leq$  overlap

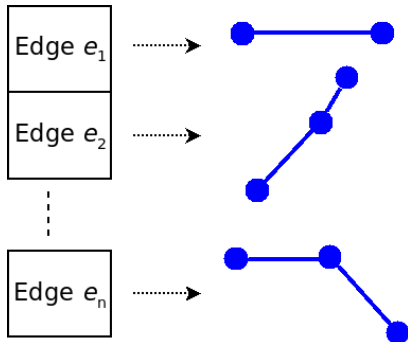
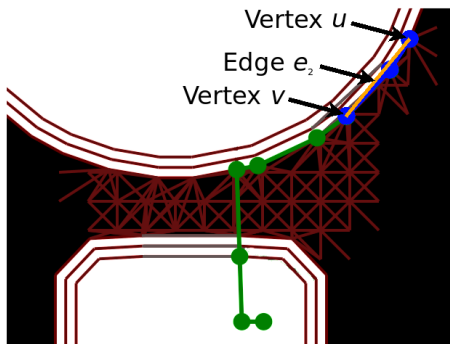


# 3D Routing



- ▶ overlap = 2mm
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# 3D Routing



- ▶ overlap = 2mm
- ▶ grid\_step\_distance ≤ overlap

# 3D Routing - Results

Introduction

Hardware

Related Work

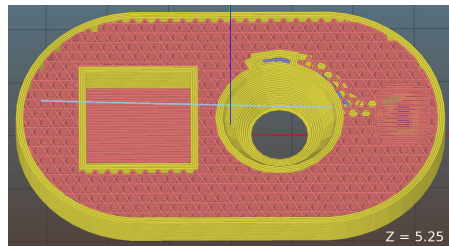
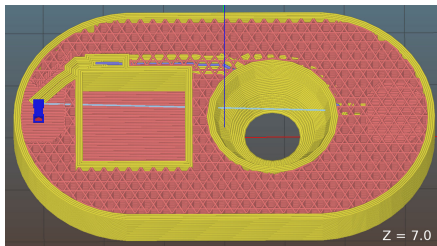
CAD / CAM Software

**Routing**

Inspection

Evaluation

Conclusion



# Collision Avoidance

Introduction

Hardware

Related Work

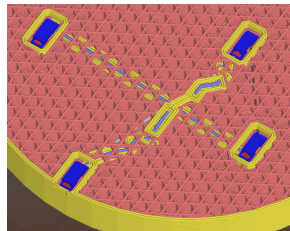
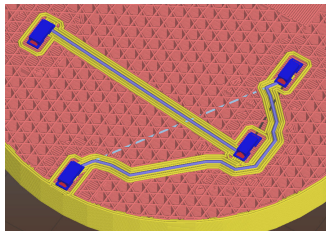
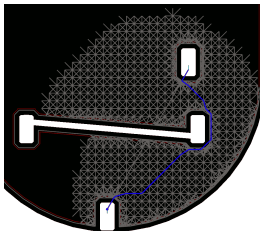
CAD / CAM Software

**Routing**

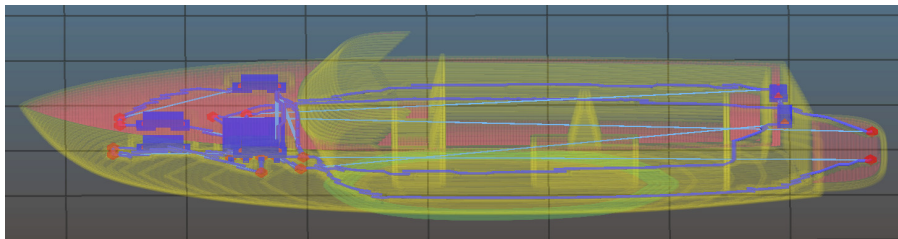
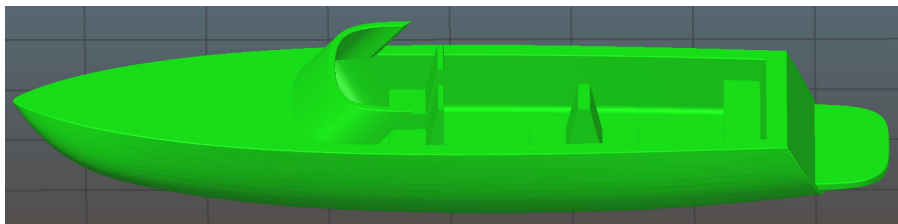
Inspection

Evaluation

Conclusion



# 3D Routing Results



## Inspection

[4]: Florens Wasserfall, Norman Hendrich, and Daniel Ahlers. Optical In-Situ Verification of 3D-Printed Electronic Circuits. In *Proceedings of the 15th IEEE Conference on Automation Science and Engineering (CASE)*, pages 1302–1307, Vancouver, 2019

# Common Issues

Introduction

Hardware

Related Work

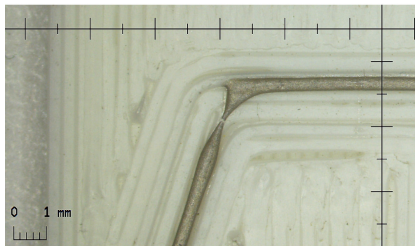
CAD / CAM Software

Routing

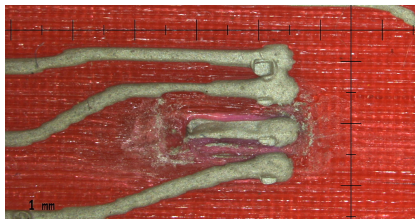
Inspection

Evaluation

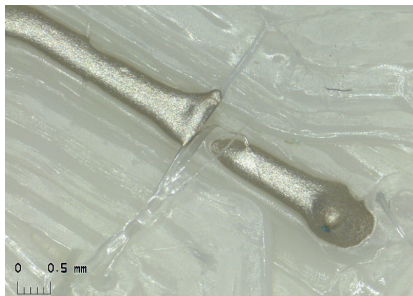
Conclusion



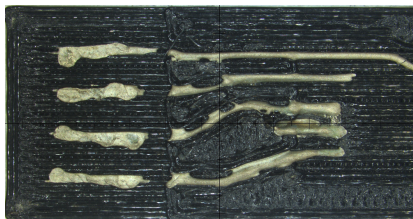
Underextrusion



Short circuit

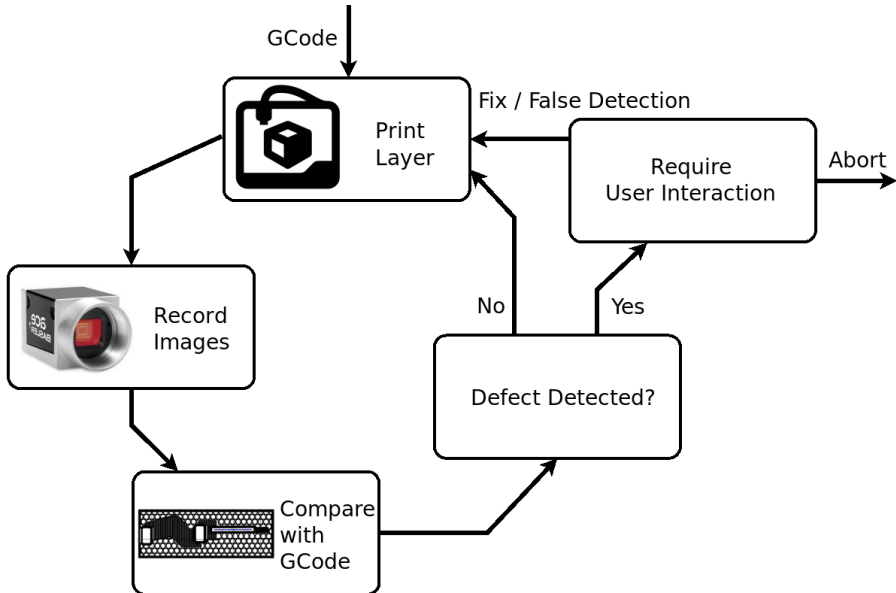


Plastic strand



Surface structure

# Detect Failure During Print-Time





# Identify Ink vs. Plastic

Introduction

Hardware

Related Work

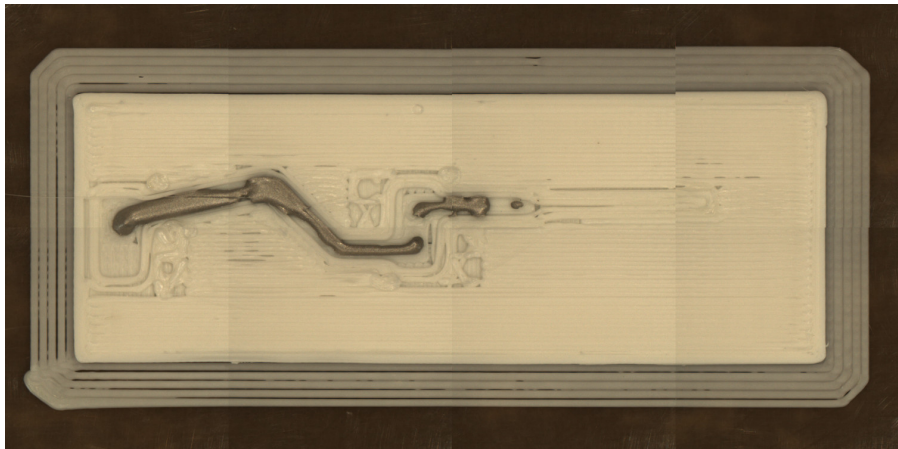
CAD / CAM Software

Routing

Inspection

Evaluation

Conclusion



Raw image

# Identify Ink vs. Plastic

Introduction

Hardware

Related Work

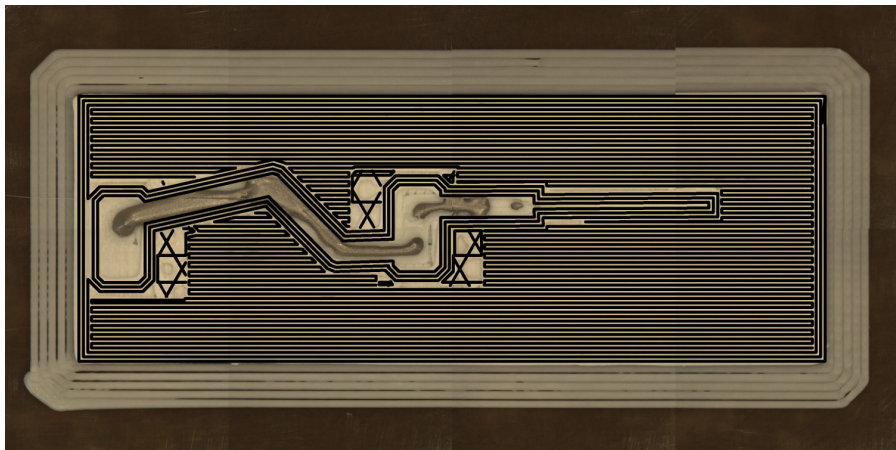
CAD / CAM Software

Routing

Inspection

Evaluation

Conclusion



Overlay T0 (plastic extruder)

# Identify Ink vs. Plastic

Introduction

Hardware

Related Work

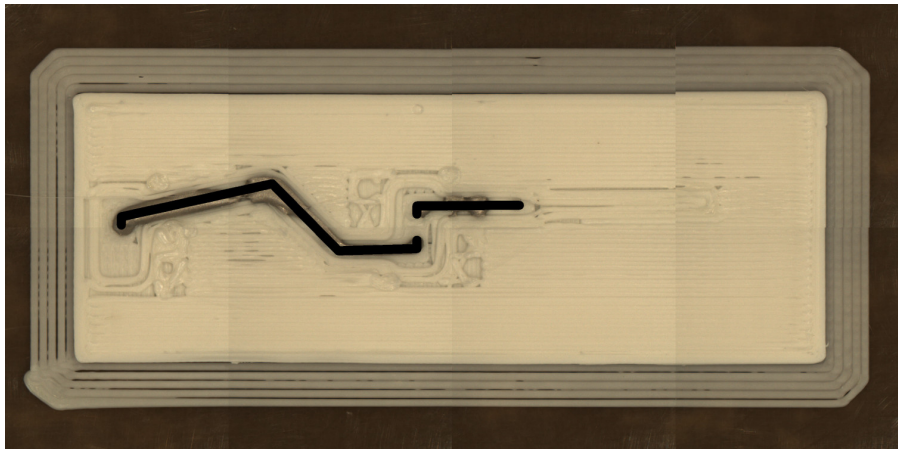
CAD / CAM Software

Routing

Inspection

Evaluation

Conclusion



Overlay T1 (conductive extruder)

# Detection Results

Introduction

Hardware

Related Work

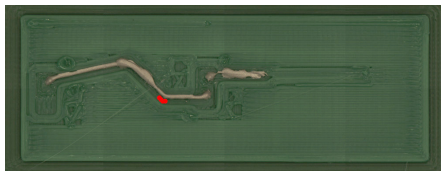
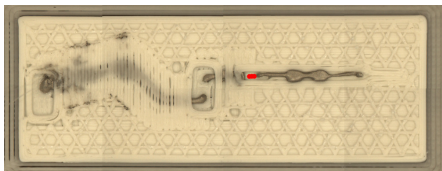
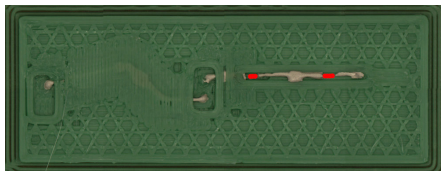
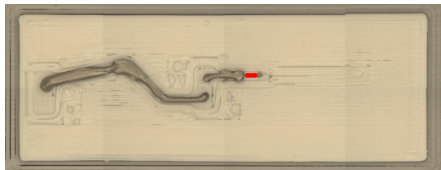
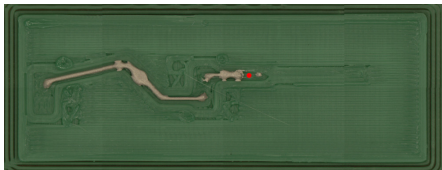
CAD / CAM Software

Routing

Inspection

Evaluation

Conclusion



## Evaluation

- [5]: Florens Wasserfall, Norman Hendrich, Fabian Fiedler, and Jianwei Zhang.  
3D-Printed Low-Cost Modular Force Sensors. In *Proceedings of the 20th Intl. Conference on Climbing and Walking Robots (CLAWAR)*, pages 485–492, Porto, 2017

# Instrumented Object

Introduction

Hardware

Related Work

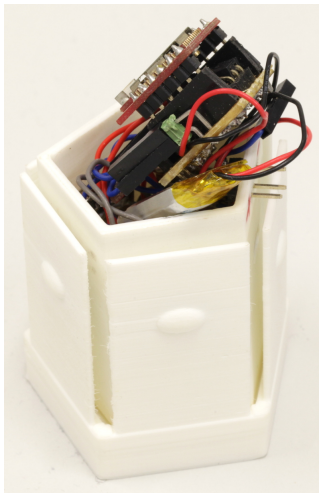
CAD / CAM Software

Routing

Inspection

**Evaluation**

Conclusion



# Instrumented Object

Introduction

Hardware

Related Work

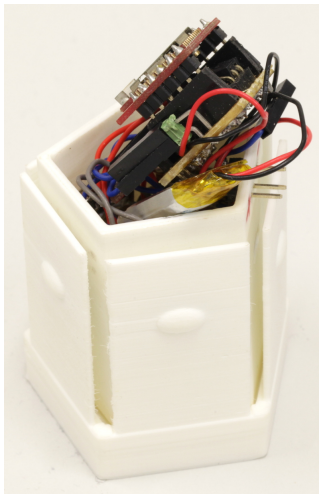
CAD / CAM Software

Routing

Inspection

Evaluation

Conclusion



# Instrumented Object

Introduction

Hardware

Related Work

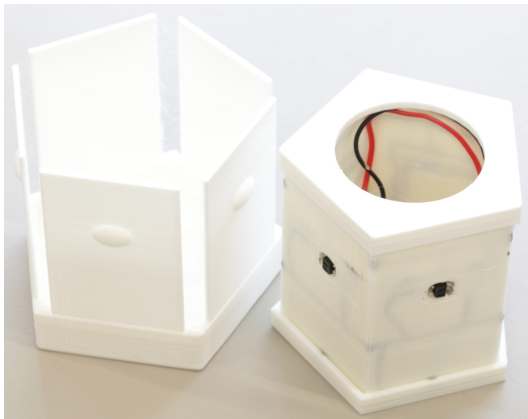
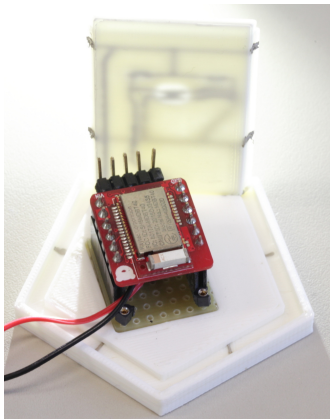
CAD / CAM Software

Routing

Inspection

Evaluation

Conclusion





# Instrumented Object – Demo

Introduction

Hardware

Related Work

CAD / CAM Software

Routing

Inspection

**Evaluation**

Conclusion



# Integrated User Interface

Introduction

Hardware

Related Work

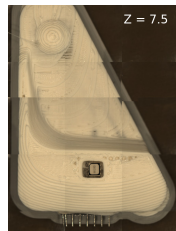
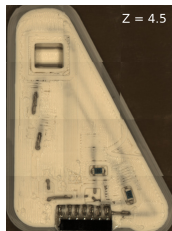
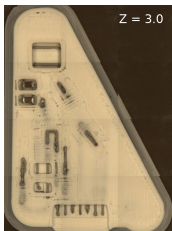
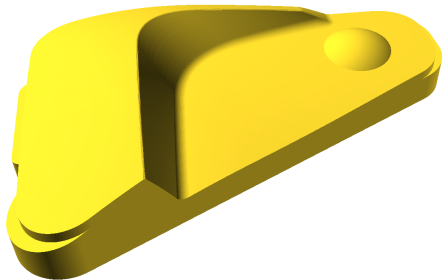
CAD / CAM Software

Routing

Inspection

Evaluation

Conclusion



# 3D CT Image

Introduction

Hardware

Related Work

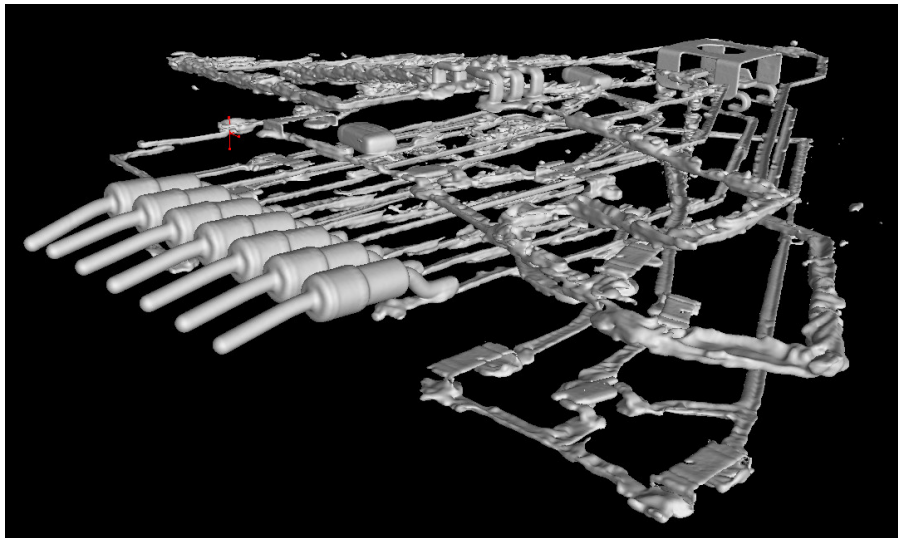
CAD / CAM Software

Routing

Inspection

Evaluation

Conclusion



## Contributions

- ▶ Design- / Routing-Algorithms
- ▶ Toolchain for 3D-printed electronics
- ▶ Approach for automated visual process monitoring

## Contributions

- ▶ Design- / Routing-Algorithms
- ▶ Toolchain for 3D-printed electronics
- ▶ Approach for automated visual process monitoring

## Future Work

- ▶ Going professional!
- ▶ More reliable hardware
- ▶ 5-Axis system
- ▶ Routing on object surface

## Download / Sourcecode:

*[tams.informatik.uni-hamburg.de/research/3d-printing/conductive\\_printing](https://tams.informatik.uni-hamburg.de/research/3d-printing/conductive_printing)*

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*[github.com/platsch/Slic3r](https://github.com/platsch/Slic3r)*

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*[github.com/platsch/OctoPNP](https://github.com/platsch/OctoPNP)*

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*[github.com/platsch/OctoCameraDocumentation](https://github.com/platsch/OctoCameraDocumentation)*

- [1] Florens Wasserfall. Embedding of SMD populated circuits into FDM printed objects. In *Proceedings of the 26th International Solid Freeform Fabrication Symposium*, pages 180–189, 2015.
- [2] Florens Wasserfall, Daniel Ahlers, Norman Hendrich, and Jianwei Zhang. 3D-Printable Electronics - Integration of SMD Placement and Wiring into the Slicing Process for FDM Fabrication. In *Proceedings of the 27th International Solid Freeform Fabrication Symposium*, pages 1826–1837, Austin, 2016.
- [3] Florens Wasserfall. Topology-Aware Routing of Electric Wires in FDM-Printed Objects. In *Proceedings of the 29th International Solid Freeform Fabrication Symposium*, pages 1649–1659, Austin, 2018.
- [4] Florens Wasserfall, Norman Hendrich, and Daniel Ahlers. Optical In-Situ Verification of 3D-Printed Electronic Circuits. In *Proceedings of the 15th IEEE Conference on Automation Science and Engineering (CASE)*, pages 1302–1307, Vancouver, 2019.
- [5] Florens Wasserfall, Norman Hendrich, Fabian Fiedler, and Jianwei Zhang. 3D-Printed Low-Cost Modular Force Sensors. In *Proceedings of the 20th Intl. Conference on Climbing and Walking Robots (CLAWAR)*, pages 485–492, Porto, 2017.
- [6] Florens Wasserfall, Norman Hendrich, and Jianwei Zhang. Adaptive Slicing for the FDM Process Revisited. In *Proceedings of the 13th IEEE Conference on Automation Science and Engineering (CASE)*, pages 49–54, Xi'an, 2017.

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- [7] Daniel Ahlers, Florens Wasserfall, Norman Hendrich, and Jianwei Zhang. 3D Printing of Nonplanar Layers for Smooth Surface Generation. In *Proceedings of the 15th IEEE Conference on Automation Science and Engineering (CASE)*, pages 1737–1743, Vancouver, 2019.
- [8] Marc Bestmann, Florens Wasserfall, Norman Hendrich, and Jianwei Zhang. Replacing Cables on Robotic Arms by Using Serial via Bluetooth. In *Proceedings of the IEEE Conference on Robotics and Biomimetics (ROBIO)*, pages 189–195, Macao, 2017.
- [9] Marc Bestmann, Bente Reichardt, and Florens Wasserfall. Hambot: An open source robot for robocup soccer. In *19'th RoboCup international Symposium, Hefei*, 2015.
- [10] Dennis Krupke, Florens Wasserfall, Norman Hendrich, and Jianwei Zhang. Printable modular robot: an application of rapid prototyping for flexible robot design. *Industrial Robot: An International Journal*, 42(2):149–155, 2015.