

# Building Spoken Dialogue Systems for Embodied Agents Lecture 3

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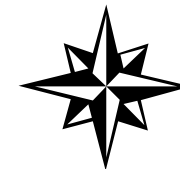
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# Outline of the course

- Part I: Natural Language Processing
  - Practical: designing a grammar for a fragment of English in a robot domain
- Part II: Inference and Interpretation
  - Practical: extending the Curt system
- **Part III: Dialogue and Engagement**

# This Lecture

- Communication is more than just language
- Building Dialogue Systems



# Dialogue is more than just using verbal language

- Engagement
- Engagement for robots
- Mel, the Penguin Robot
- Indicators of engagements
- Simple heuristics
- Greta, the talking head

# Engagement 1/2

- “the process that two participants establish, maintain, and end during interactions they jointly undertake” (Sidner et al. 2003)
- Supported by conversation, collaboration on a task, and gestural behaviour that convey connection between participants

# Engagement 2/2

- The means by which one participant tells the other that (s)he intends to continue the interaction (or abandon it)
- Not only speaker, also hearer (gestures)
- Grounding is part of engagement
- Turn taking
- Compare face-to-face vs. telephone
- Cultural differences

# Engagement for Robots

- A robot must convey such gestures, and also interpret similar behaviour from its conversational partners
- Proper generation and interpretation of engagements enhances success of conversation (and collaboration)
- Inappropriate behaviour can cause misinterpretations (examples)

# Engagement Capabilities for a Robot

- Initiate, maintain, and disengage in conversation
- Dialogue management
  - turn taking
  - Interpreting intentions and goals of other participants
- Examples: where to look at the end of the turn



## Example: Mel (Sidner et al. 2003)

- Mel: Robot which looks like a penguin
- Uses head, wings and beak for gestures
- Mel's hardware
  - Face detection
  - Sound location
  - Object Recognition

# Mel the Penguin Robot

- Considers choices at every point of the conversation for
  - Head-movement
  - Gaze
  - Use of pointing
- Determines changes in head-movements, gaze and use of pointing of the participant

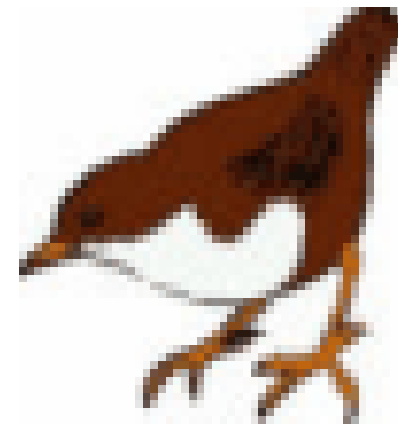
# Indicators of Engagement

- Looking at the speaker is evidence for engagement
- Looking around the room (for more than brief moments) indicates disinterest and possible the intention to disengage
- However, looking at objects relevant to the conversation are not indicators of disengagement!

## Heuristics for implementing engagement

- For a hearer: do what the speaker does!
  - Look wherever the speaker looks
  - Look at speaker if (s)he looks at you
  - Look at relevant objects of the discussion

# Building Spoken Dialogue Systems with DIPPER



# DIPPER...



- Offers an architecture for prototyping spoken dialogue systems
- Is based on the Open Agent Architecture
- Has its own Dialogue Management Component, based on the information-state approach (Trindi)

# Overview of this Talk

- The Dipper environment
  - Open Agent Architecture (OAA)
  - Agents and Solvables
  - Dialogue Management in Dipper
- The Information-state update approach
  - Information states
  - Update Language
- Comparison with TrindiKit
- Working with Dipper

# 1. The DIPPER environment

- How to build a dialogue system using and adapting off-the-shelf components that
  - need to interact with each other
  - are implemented in various programming languages
  - are running on various platforms?
- Examples:
  - Festival (C++), Nuance (C,C++,Java)
  - Parsing, Context Resolution (Prolog)
  - Dialogue Management (Prolog), O-Plan (Lisp)



# The Open Agent Architecture

- Framework for integrating a community of heterogeneous software agents in a distributed environment
- Agents can be created in multiple programming languages on different platforms
- Agents can be spread across a computer network
- Agents can cooperate or compete on tasks in parallel

# OAA Philosophy

- express requests in terms of *what is to be done* in terms of **solvable**s without requiring specifying
  - who is to do the work
  - how it should be performed
- requester delegates control for meeting a goal with the **facilitator** (coordinating the activities of agents)
- develop components of application separately by wrapping them into **agents**

# OAA Availability

- Developed by SRI AIC, freely available.
- Current Version OAA-2.1 (released Sept'01)
  - libraries for Java, C, C++, Prolog, and WebL
  - Solaris, Linux, and Windows 9x/NT
- OAA-1.0
  - more languages (Lisp, Basic, Delphi, Perl *etc.*)
  - SunOs 4.1.3, SGI IRIX
- OAA-2.1 Facilitator provides backward compatibility
  - OOA-1 and OAA-2 agents can co-exist
- Active community exists

# OAA Agent Types

- *requester*: specifies goal to the facilitator, provides advice on how it should be met
- *providers*: register their capabilities with the facilitator, know what services they provide, understand limits of their ability to do so
- *facilitator*: maintains a list of provider agents and a set of general strategies for meeting goals

# Prolog wrapper for requester

```
:- use_module(_, com_tcp, all).
:- use_module(oaa, all).

runtime_entry(start) :-
    com_Connect(parent, [], _Address),
    oaa:oaa_Register(parent, prolog_testagent2, [], []),
    oaa:oaa_Ready(true).

:- runtime_entry(start).

% request service with: oaa_Solve(test(A,B), Z).
```

# Prolog wrapper for provider

```
:- use_module(_, com_tcp, all).
:- use_module(oaa, all).

runtime_entry(start) :-
    com_Connect(parent, [], _Address),
    oaa:oaa_Register(parent, prolog_testagent1, [test(_A,_B)], []),
    oaa:oaa_RegisterCallback(app_do_event, user:oaa_AppDoEvent),
    oaa:oaa_MainLoop(true).

oaa_AppDoEvent(test(A,B), Params) :-
    write(['I have been called with ', A, B]), nl,
    highly_complex_prolog_code(A,B).

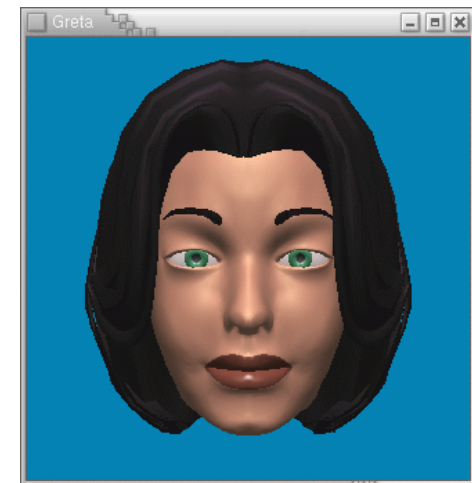
highly_complex_prolog_code(A,B) :-
    A = 'a',
    B = 'b'.

:- runtime_entry(start).
```

# Dipper: Input/Output Agents



- ASR: Dipper supports agent “wrappers” for **Nuance 7.0 and 8.0** with solvables:
  - `recognize (+Grammar, +Time, -Result)`
- Synthesis: **Festival, rVoice, Greta**, with solvables:
  - `text2speech (+Text)`
  - `sable2speech (+SABLE)`
  - `play_apml (+APML)`



# Dipper: Supporting Agents

- OAA comes itself with Gemini
  - parsing and generation
- Dipper provides further agents
  - DRT stuff (resolution, inference)
  - Theorem proving (SPASS, MACE)
  - Content planning (O-Plan)
  - X-10 Device control (Heyu)



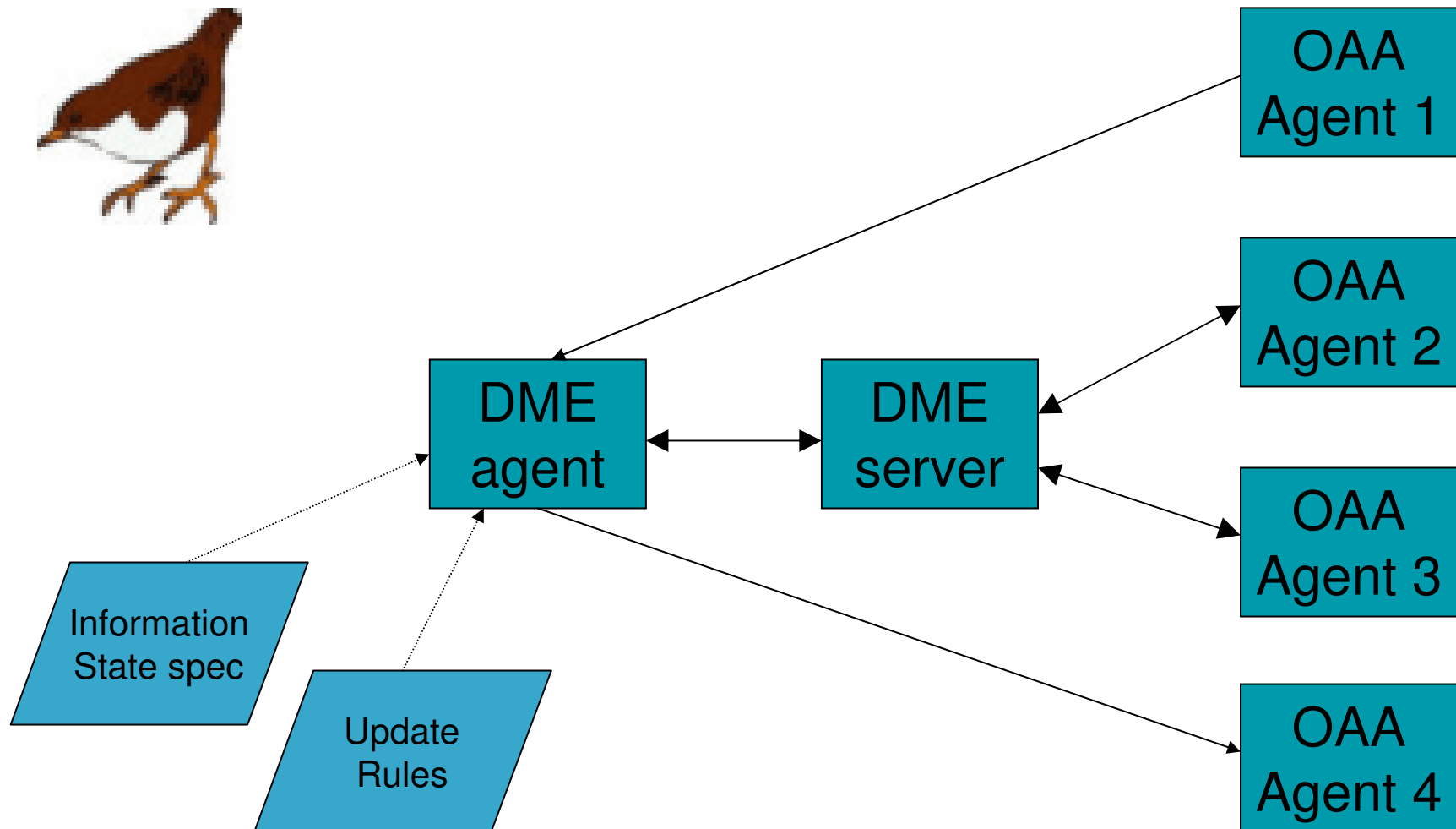
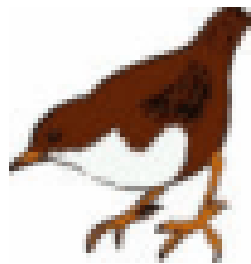
# Dipper: Dialogue Management Agents

- Dialogue management forms the heart of a dialogue system:
  - Reading (multi-modal) input modalities
  - Updating the current state of the dialogue
  - Deciding what to do next
  - Generating output
- It is the most complex agent!
- Dipper implements dialogue management as two agents: the DME, and the DME server

# The Dialogue Move Engine

- The DME agent, with solvables:
  - `check_conds (+Conditions)`
  - `apply_effects (+Effects)`
- The DME server mediates between the DME agents and other agents
  - `dme (+Call, +Effects)`
- Multiple threads possible

# Dipper DME functionality



## 2. The Information-State Approach

- Some History
- The Information-state Approach
- Specifying Information States
- The Dipper Update Language
- A simple example

# Some History

- Traditional approaches:
  - **Dialogue state** approaches (dialogue dynamics specified by a set of states and transitions modelling dialogue moves)
  - **Plan-based** approaches (used for more complex tasks showing flexible dialogue behaviour)
- Information-state approaches combine the merits of both approaches

# Information-state Approaches

- Declarative representation of dialogue modelling
- Components:
  - Specification of contents of the information state of the dialogue
  - Datatypes to structure information
  - A set of update rules
  - Control strategy for information state updates
- First implementation: TrindiKit
- Dipper builds on TrindiKit

# Specifying Information States

- The information state “*represents the information necessary to distinguish it from other dialogues, representing the cumulative additions from previous actions in the dialogue, and motivating further action*” (Traum et al., 1999)
- Compare: mental model, discourse context, state of affairs, conversational score, etc.
- Dipper uses TrindiKit technology representing information states

# Example: Information State Definition

Datatypes: record, stack, queue, atomic, drs

```
is:record([grammar:atomic,  
          input:queue(atomic),  
          sem:stack(record([int:atomic,  
                           context:drs]))])])
```



# Information State based on Ginzburg's QUD (Godis)

- `Private`:
  - `Bel`: set of propositions (according to system)
  - `Agenda`: stack of actions (short-term intentions)
  - `Plan`: stack of actions (long-term dialogue goals)
  - `Tmp`: copy of `Shared`
- `Shared`:
  - `Bel`: set of propositions (shared by participants)
  - `QUD`: stack of questions under discussion
  - `LM`: latest move (speaker, move, content)

# The Dipper Update Language

- Update Rules have 3 components
  - **Name** (identifier)
  - **Conditions** (a set of 'tests' on the current information state)
  - **Effects** (an ordered set of operations on the information state, resulting in a new state)
- Conditions and effects are defined by the Dipper Update Language

# Standard vs Anchored Terms

- Standard Terms: basic definitions of the datatypes (constants, stacks, queues, records)
- Special term:  $i_s$ , referring to the complete information state
- Anchored Terms
  - $i_s, T^F, \text{first}(T), \text{last}(T), \text{top}(T), \text{member}(T)$

# Example: Anchored Terms

- Information State (s)

is: grammar: '.Yesno'

input: <>

sem: < int: model(...)

context: drs([X, Y], ...) >

- Reference: [.]s

– [is^grammar]<sub>s</sub> = '.Yesno'

– [grammar]<sub>s</sub> = grammar

– [top(is^sem)^context]<sub>s</sub> = drs([X, Y], ...)

– [top(sem)^context]<sub>s</sub> = *undefined*

# Conditions and Effects

- **Conditions**
  - $T1=T2, T1\neq T2$
  - `empty(T1), non_empty(T1)`
- **Effects (T1 anchored)**
  - `assign(T1,T2), clear(T1), pop(T1),  
push(T1,T2), dequeue(T1), enqueue(T1,T2)`
  - `solve(S(...,Ti,...),Effects)`

# A Simple Example: Parrot

- We will use the following information state structure:

```
is:record([input:queue(atomic),  
          listening:atomic,  
          output:queue(atomic)])
```

- Four agents:
  - ASR, SYN, the DME agent and the DME server



# Update Rules for Parrot

```
urule(timeout,  
    [first(is^input)=timeout],  
    [dequeue(is^input)]).
```

```
urule(process,  
    [non_empty(is^input)],  
    [enqueue(is^output,first(is^input)),  
    dequeue(is^input)]).
```

```
urule(synthesise,  
    [non_empty(is^output)],  
    [solve(text2speech(first(is^output)),[]),  
    dequeue(is^output)]).
```

```
urule(recognise,  
    [is^listening=no],  
    [solve(recognise(`.Gram',10,X),  
        [enqueue(is^input,X),assign(is^listening,no)]),  
    assign(is^listening,yes)]).
```

# 3. Working with DIPPER

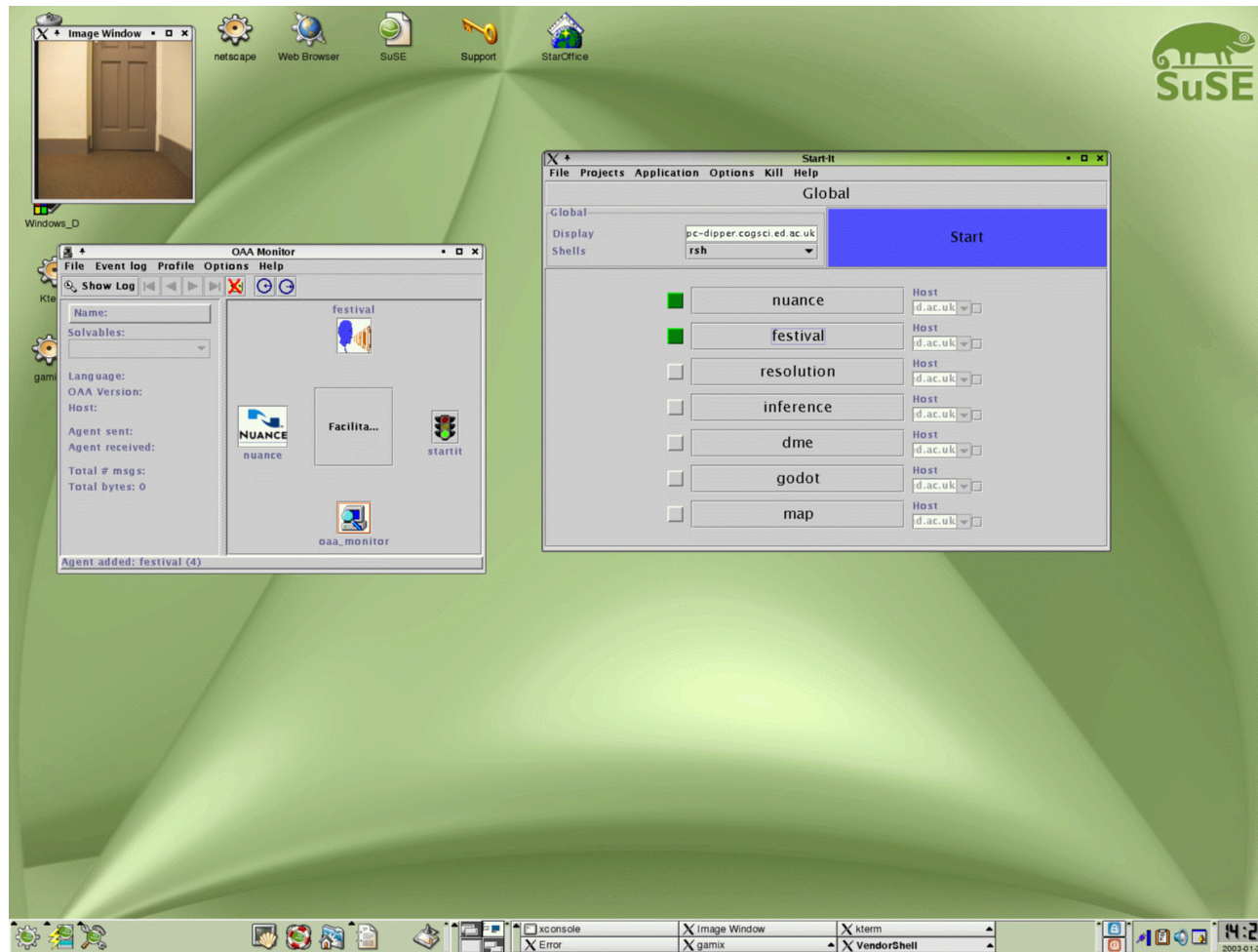
- Prototyping
  - How to build and run a DIPPER application
  - The startit.sh and monitor.sh
- Debugging
  - Testing and debugging of information-state approaches can be difficult
- DIPPER prototypes

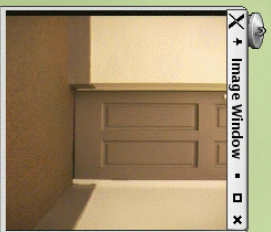


# How to build and run a DIPPER application?

- Set up your machine for using OAA (and Nuance)
- Decide which components you want to use and specify an OAA config file
- Specify information state and update rules
- Start the OAA facilitator (fac.sh) and the OAA application manager (startit.sh)

# OAA tools (startit.sh and monitor.sh)





- netescape
- Web Browser
- SUSE
- Support
- StarOffice

OAA Monitor

File Event log Profile Options Help

Show Log

Name:

Solvable:

Language:

OAA Version:

Host:

Agent sent:

Agent received:

Total # msgs:

Total Bytes: 0

Facilita...

godot

semantic\_map

startit

gaa\_monitor

nuance

resolution

robot\_oaa

inference

mate

spass

dme

File Projects Application Options Kill

Global

Display

pc-dipper.cogsci.ed

fsh

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fe

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r

DIPPER TRINIDI DME

Information State

Init

Prev

Next

Last

```

ist:
  history: {}
  grammar:
    sentence: {}
    super: {}
    confidence:
      current: 0
      history:
        yes: {}
        no: {}
  nextmove:
    utterance: {}
    act: {}
  lastmove:
    string: {}
    act: {}
    udri: {}
    cont: {}
    inti: {}
  inti:
    drai: {}
    modal: {}
  
```

Update Rule

Spy

Name: none

Conditions: none

Effects: none

Dialogue Move Engine

Go!

Stop

Step

Quit

System tray and taskbar area containing icons for network, volume, and system clock, along with a taskbar showing open applications like 'xcconsole', 'Image Window', 'DIPPER TRINIDI DME', 'Kitem', 'VendorShell', and 'XTerm'.



# The DIPPER GUI

The screenshot shows the DIPPER TRINDI DME GUI with the following components:

- Information State:** A text area containing:

```
nextmoves:
  utterance: ()
  act: ()
lastmoves:
  string: < [word(when,72),word(are,33),word(you,75)] >
  act: < query >
  udr: <>
  conf: < 68 >
  int: <>
int:
  drs: <
```
- Diagram:** A graphical representation of the information state with boxes and labels:
  - A box labeled "L x1." containing "x3 x2", "system(x3)", and "user(x2)".
  - A box labeled "x4" containing "location(x4)".
  - A box labeled "x5" containing "present(x5)".
  - A nested box labeled "x5:" containing "x6", "rel(x6,x4)", and "x3 = x6".
  - Labels "(+)" and "<?>" are placed between the boxes.
- Update Rule:** A text area containing:

```
Name: consistent
Conditions: [non_empty(is^lastmoves^int),empty(is^int^model),empty(is^int^drs)]
Effects: [prolog(pop(is^lastmoves^int)=i(_213572,_213573)),push(is^int^drs,_213572),push(is^int^model,_213573)]
```
- Dialogue Move Engine:** A text area containing "Message: stop."

# Dipper Prototypes

- D'Homme (home automation)
- IBL (route explanation to mobile robot)
- Godot (our own robot in the basement)
- Magicster (believable agent Greta)
  
- Dipper Resources:  
<http://www.ltg.ed.ac.uk/dipper>