

multi-agent robotic systems in logistics a look at kiva systems and amazon robotics

robert a. brown



Universität Hamburg

Fakultät für Mathematik, Informatik und Naturwissenschaften Fachbereich Informatik

Technische Aspekte Multimodaler Systeme

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What are Multi-Robotic Systems?

What are Multi-Robotic Systems?

he Warehouse Problem

The Kiva Warehouse

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Ribliography

exactly what they sound like!

- coordination between large groups of relatively simple robots
 - working together towards common goal
 - not necessarily cooperative or communicative
 - local strategies
- draws inspiration from swarms found in nature
 - ▶ fish, birds, ants
- cooperative systems
 - communicate goals
- self-interested systems
 - compete for resources in market-based environment

Can a thousand tiny swarming robots outsmart nature?

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https://www.youtube.com/watch?v=dDsmbwOrHJs



Brownian Motion as a PDE

$$\frac{\partial p}{\partial t} = D\Delta p$$

$$\frac{\partial p}{\partial t} = \frac{v^2}{\mu} \left(\frac{\partial^2 p}{\partial x^2} + \frac{\partial^2 p}{\partial t^2} \right)$$

...with a Poison Process

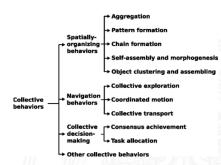
$$\frac{\mu}{2}p_{tt} + p_{tt} = \frac{v^2}{\mu}p_{xx}$$

These types of complex systems composed of simple actors can be mmodeled as dynamic systems, and studying their interaction is a field unto itself...



Dynamic System Representing a Swarm of Locusts [Ek01]

The group of robots is not just a group. It has some special characteristics, which are found in swarms of insects, that is, decentralised control, lack of synchronisation, simple and Identical Members [Ben05]



Taxonomies of Swarm Robotics [BFBD13]



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https://www.youtube.com/watch?v=ZxrzIXkPycs



The Kiva Warehouse

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The Kiva Warehouse

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- Rack
 - organized using chaotic storage
 - storage unit
- ► Robotic Agent ("Driver")
 - ▶ brings Racks to the Picker
 - returns rack to floor
- Picker
 - ► No longer fetches products



Example of a Kiva Systems Rack, Driver, and Picker [WDM07]

The Kiva Warehouse

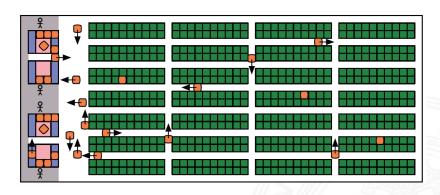
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Example of a Kiva Warehouse Floor Plan [WDM07]

https://www.youtube.com/watch?v=z_R8feyCu-M



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- actors must handle their own local tasks
 - manage resources
 - space on racks
 - space on the floor
 - robot units
- manage task assignments



Interaction between layers of Kiva Warehouse [WDM07]

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- find a path to the desired products
 - uses A* algorithm (simple, greedy, heuristic based "AI")
- navigate their environment
 - follows stickers on the floor
 - localization not needed
 - already knows map
- not hit each other



[Urb]

Kiva Systems Software

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NAVIGATION SYSTEM

A camera facing upward reads bar codes placed under inventory racks to identify them. Another camera located at the bottom of the robot views bar codes on the floor. This location information is combined with readings from other navigation sensors, such as encoders, accelerometers, and rate gyros.



POWER SYSTEM

Four lead-acid batteries power the motors and onboard electronics. When batteries run low, the robot automatically drives to a charging station.

DRIVING SYSTEM

Two brushless dc motors control independent neoprene rubber wheels, moving the robot at 1.3 meters per second.

The Kiva Warehouse "Driver" [Gui08]

Pros

- ► Greater accountability
- ► No single point of failure
- Optimization based on Popularity
- Rapid deployment
- Spatial flexibility
- Expandability

Cons

► Can't pick things up

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https://www.youtube.com/watch?v=fwghi0jpKkYq



- Multi Agent Systems work independently to complete common goal
 - ▶ may or may not communicate
 - share resources
- Kiva systems uses MAS and surprisingly simple/primitive/old algorithms
 - ► real breakthrough was the idea (and cheaper robots)
- ► Kiva Warehouses store up to 200% storage capacity and productivity, as well as accountability [Gui08]

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