

# Indoor Sound Localization

Fares Abawi



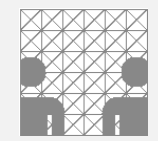
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Fachbereich Informatik  
**Technische Aspekte Multimodaler Systeme**

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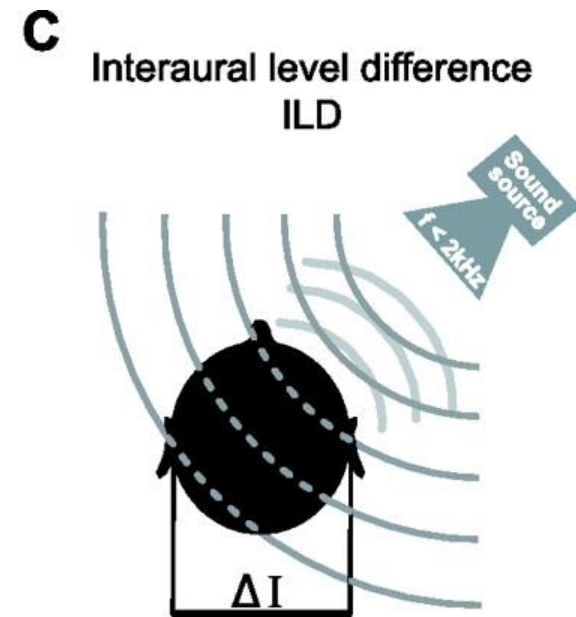
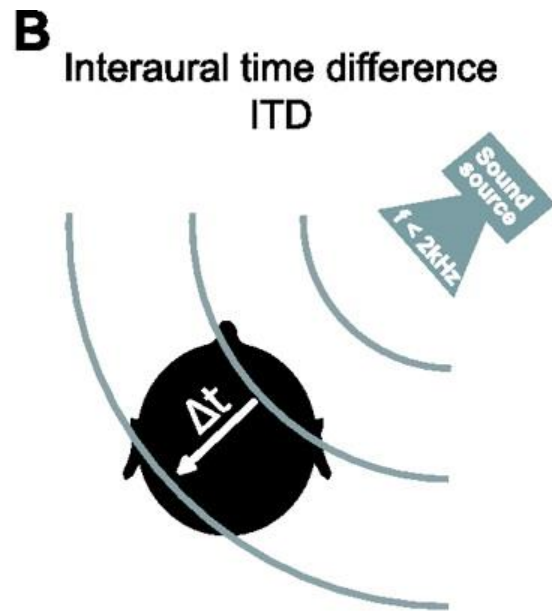
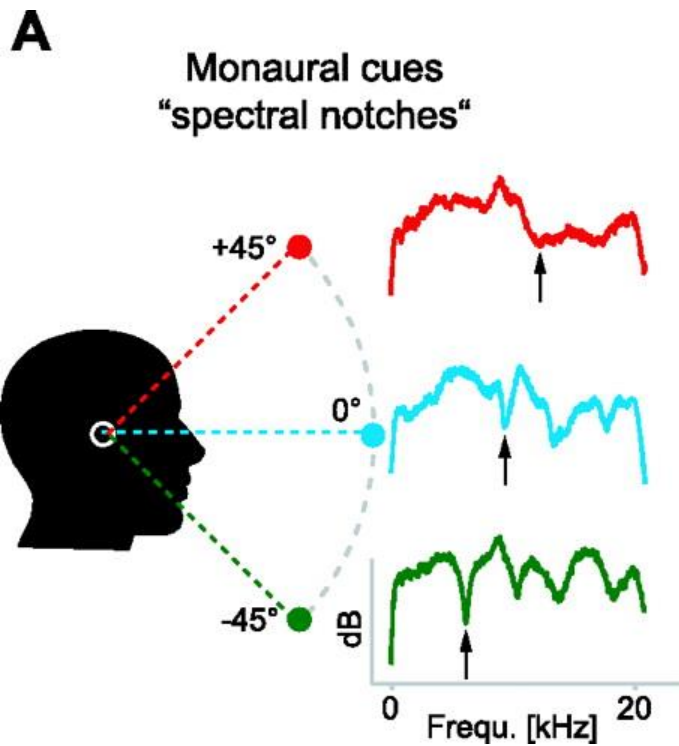


# Introduction

## Definition

Sound localization is ...

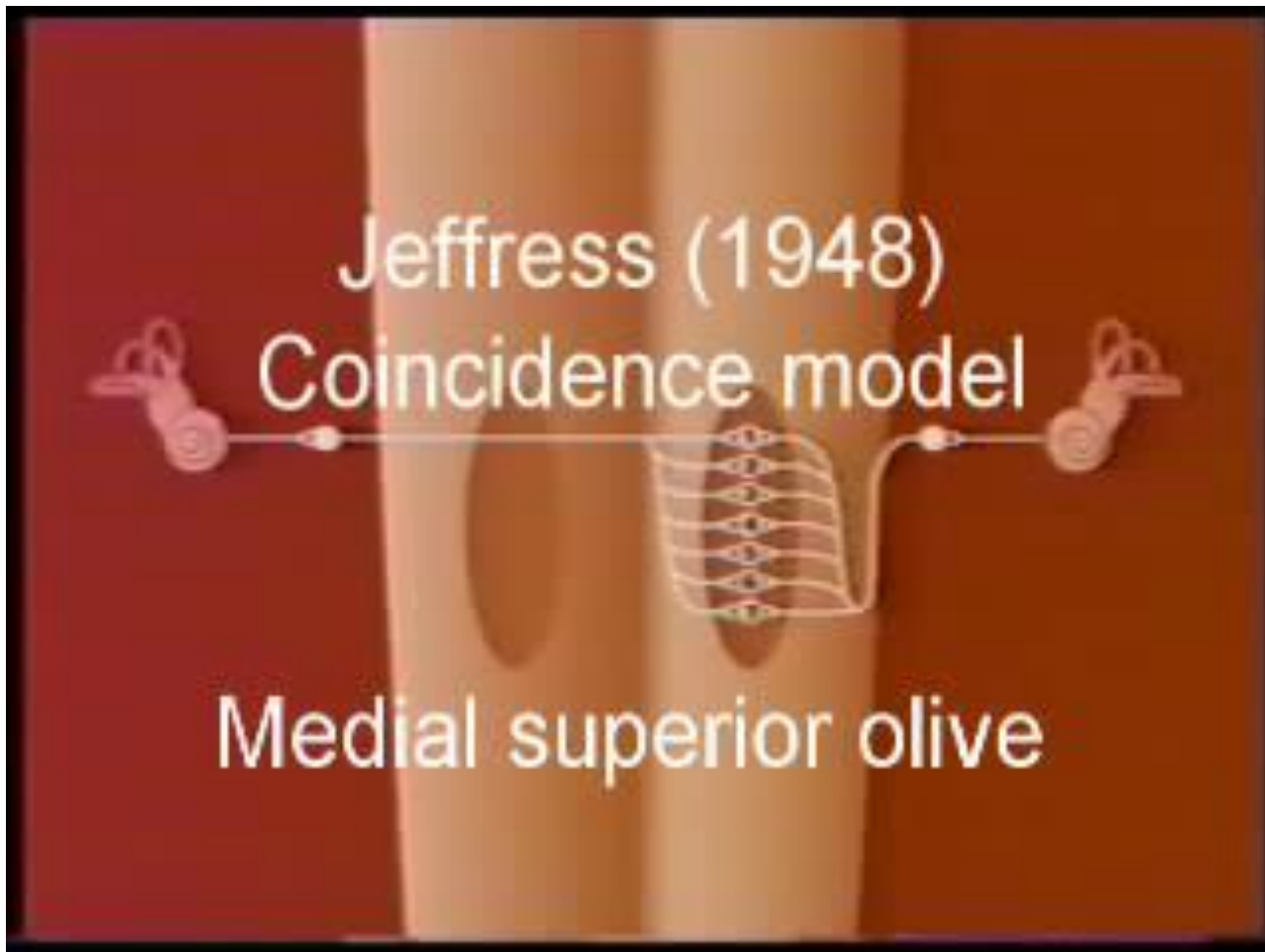
# Introduction



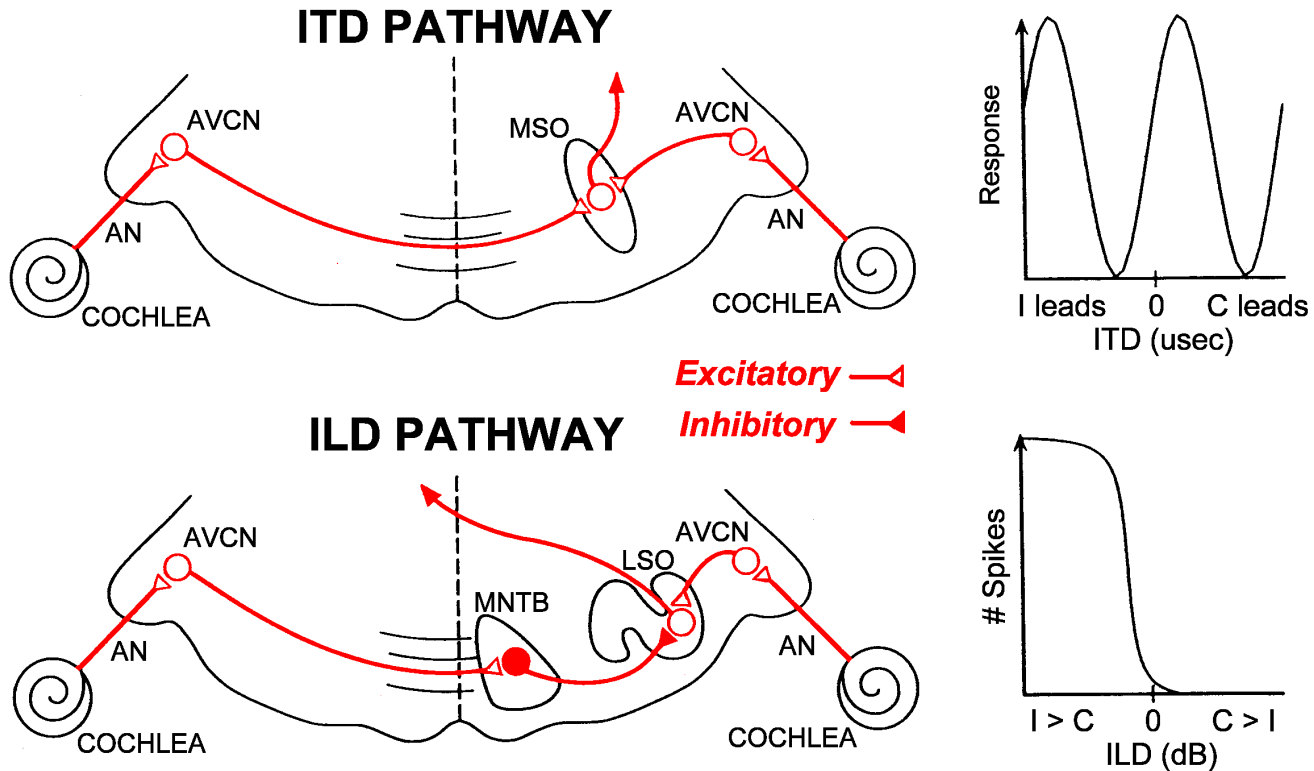
[4]

# Introduction

The Jeffress Model – Oversimplified model of the mammalian MSO  
[VIDEO] [6]



# Introduction



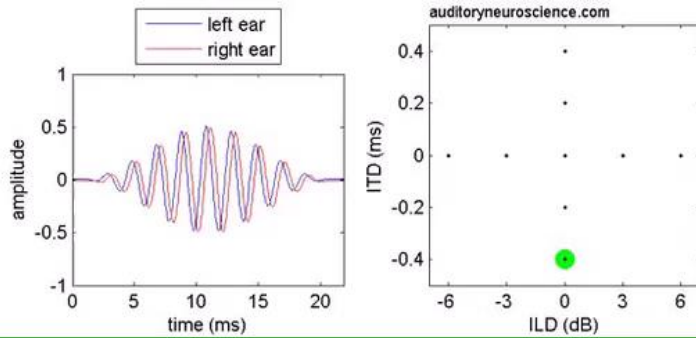
[4]

*Lateral Superior Olive* : ILD is performed  
*Medial Superior Olive* : ITD is performed

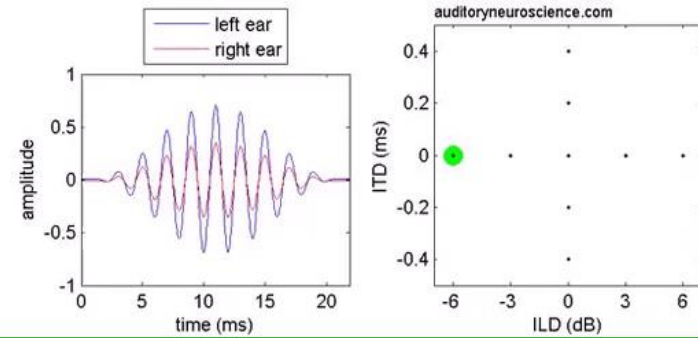
# Introduction

## Binaural cues [VIDEOS] [7]

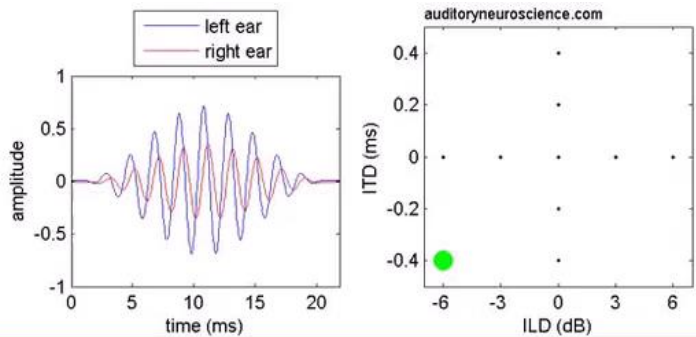
### Varying ITD



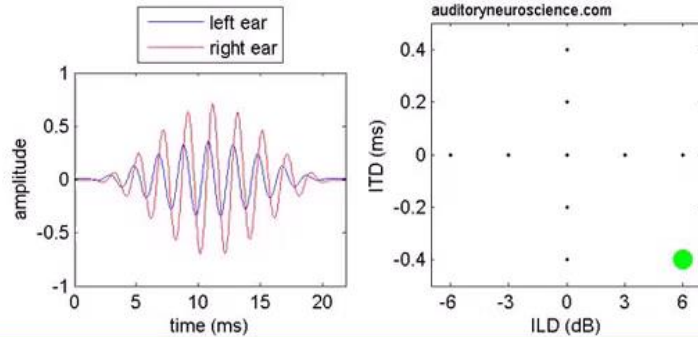
### Varying ILD

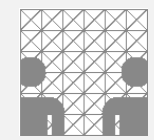


### Varying ITD & ILD



### Trading ITD off against ILD





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- ▶ **Cross-Correlation**
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# Cross-Correlation

$$(s_A \star s_B)[n] = \sum_{m=-\infty}^{\infty} s_A^*[n] s_B[n + m]$$

Get the delay between two signals by shifting one against the other  
**Multiply-> Sum-> Shift-> Repeat !**

## **Convolution Theorem:**

Convolution in the time domain is simply a multiplication in the frequency domain  
and vice versa



# Cross-Correlation

**Complexity:**

Cooley-Tuckey FFT =  $n \cdot \log(n)$

Time-Domain xcorr =  $n^2$

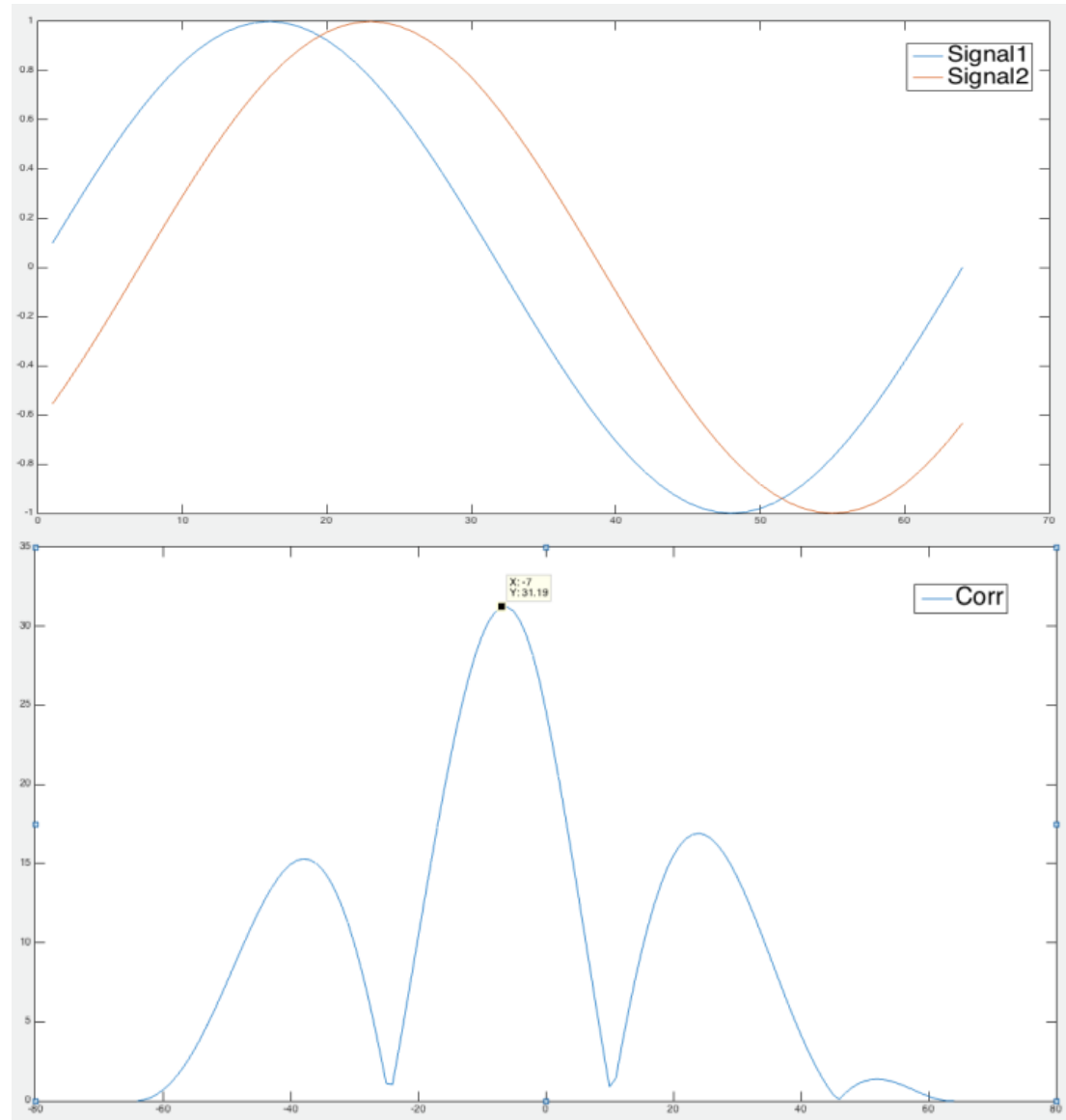
## Notes on Time->Frequency Domain Transformation

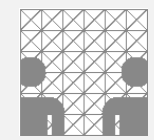
- The sampling frequency must be twice the maximum frequency a system needs to acquire, according to the **Nyquist Theorem**, in order to avoid **temporal aliasing**.
- A windowing function (**Analysis window**) must be applied to signal before transformation to avoid frequency leakage and smearing. The window can be in the form of a **Hann window**, **Hamm window** or the like.
- **Keep in mind:** The cross-correlation of two signals produces a vector with a length of both signal lengths -1. If ignored the cross-correlation will be distorted due to circular convolution.

# Cross-Correlation

Two sinusoids with a difference of 7 samples

Peak detected at  $x = -7$  after performing cross-correlation



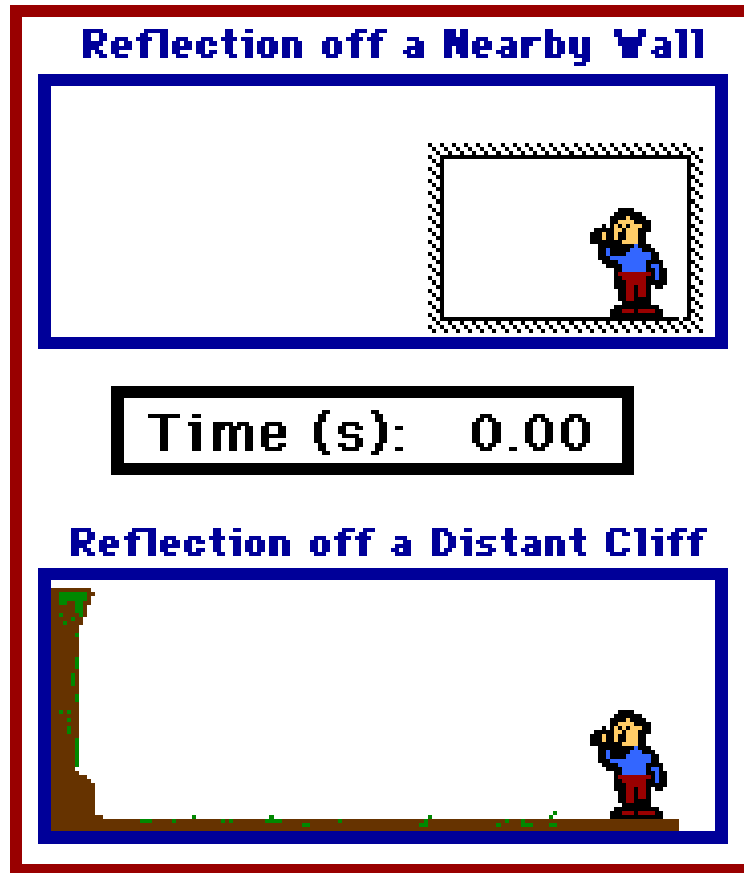


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# Quality Effecting Factors

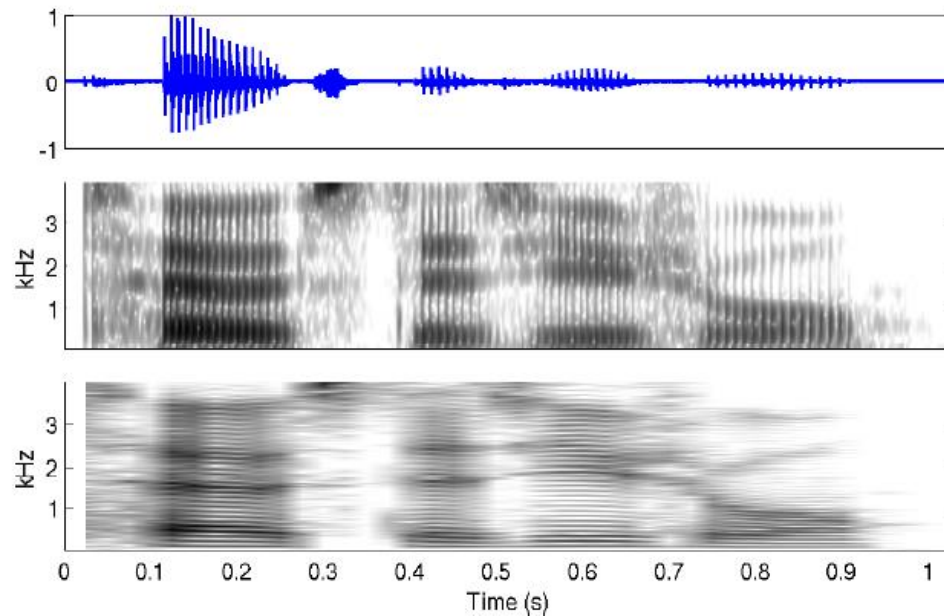
## Echo and Reverb [ANIMATION] [8]



# Quality Effecting Factors

## Noise

Noise power spectral densities can be estimated by finding the minima from time-frequency bins that do not contain speech



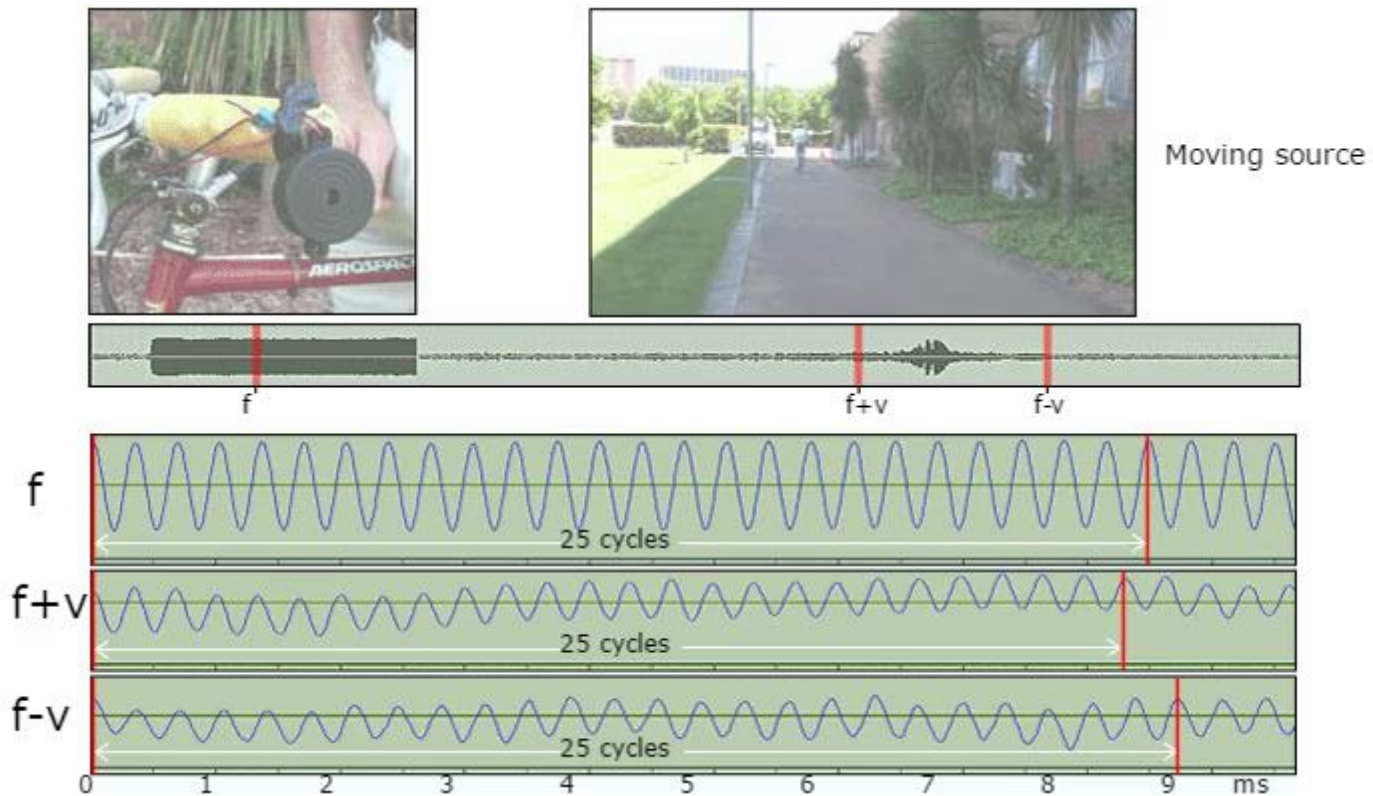
[4]

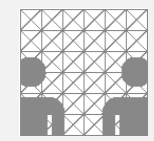
**Could this work for any sound signal ?**

**Any Environment ??**

# Quality Effecting Factors

## Doppler shift [VIDEO] [9]





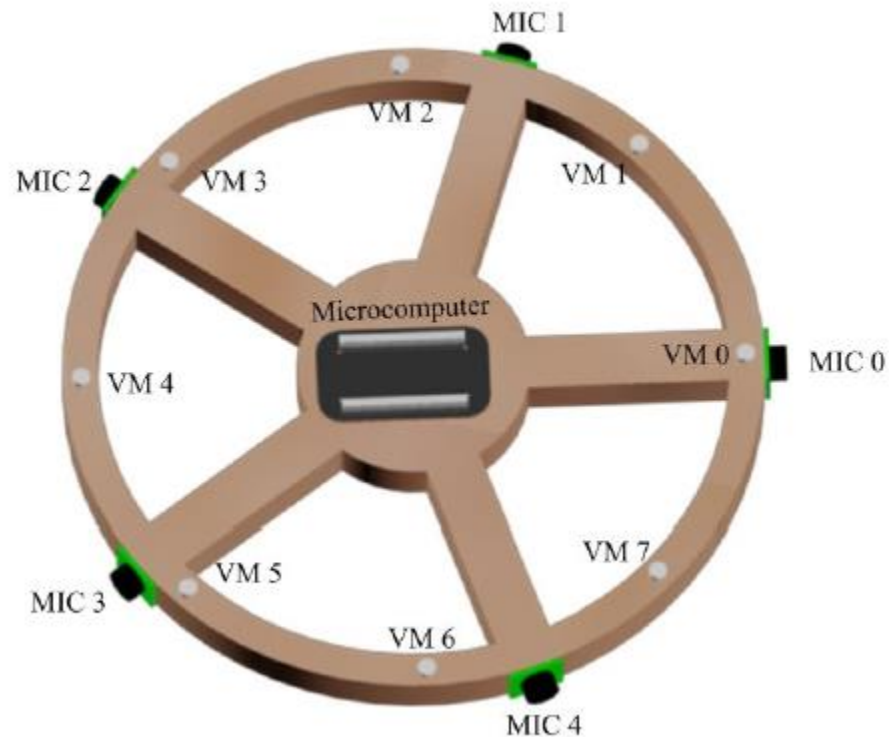
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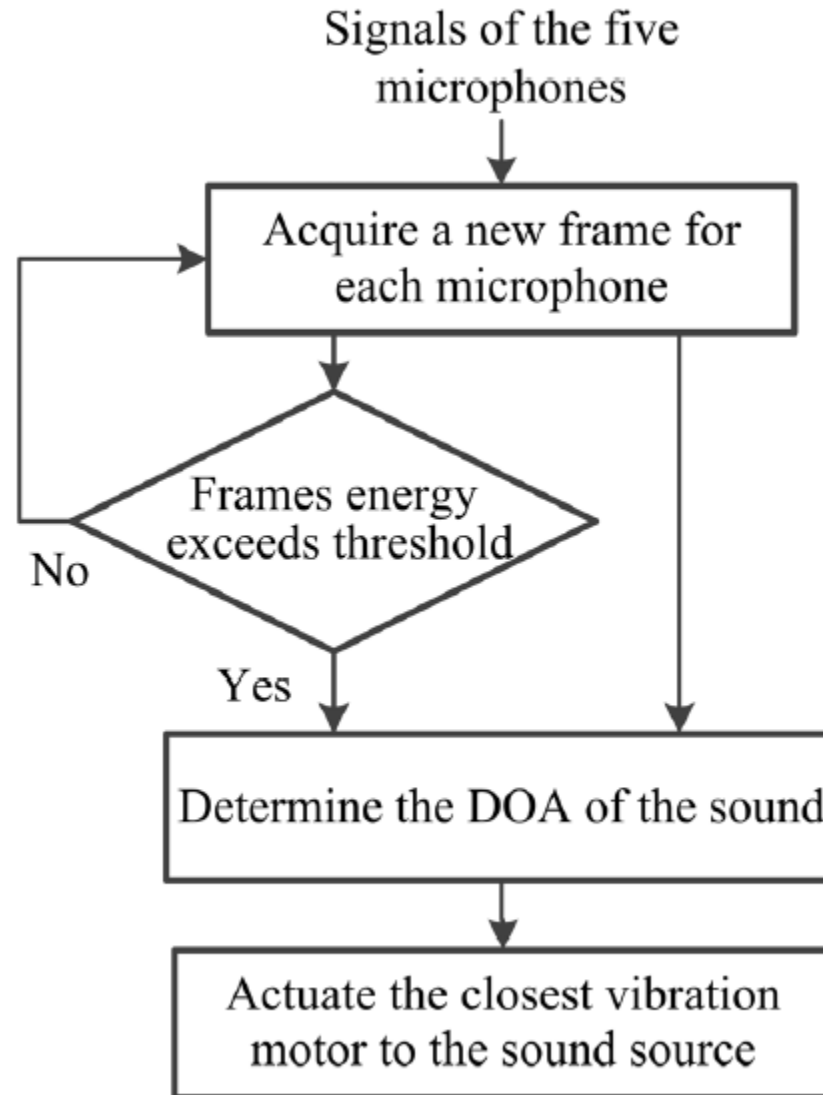


# Time Difference of Arrival

**In-house Alert Sounds Detection and Direction of Arrival Estimation to Assist People with Hearing Difficulties** [1]



# Time Difference of Arrival

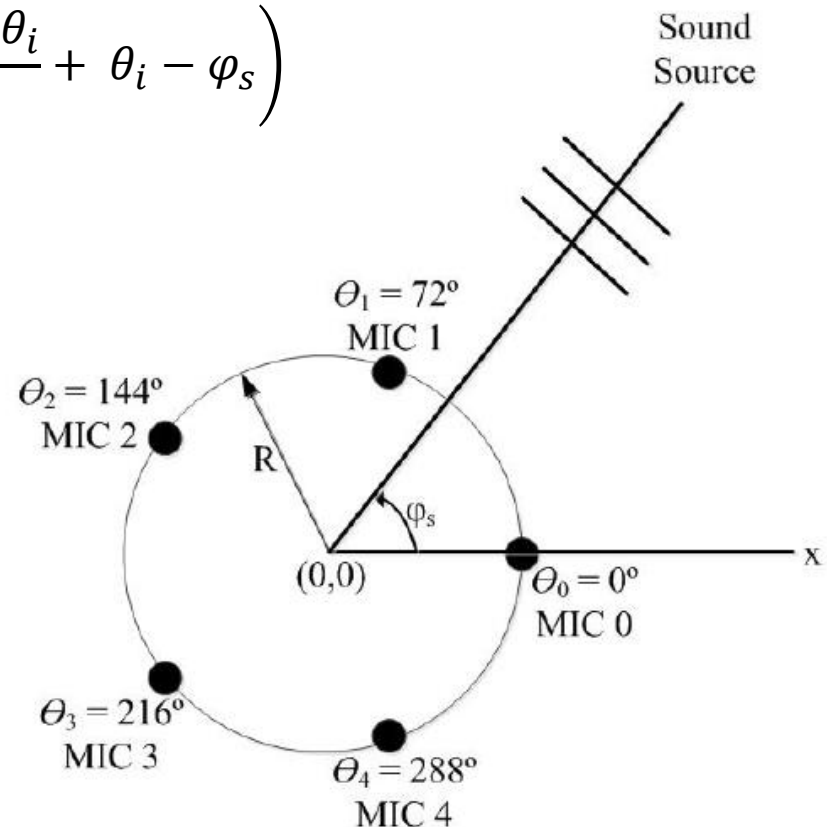


# Time Difference of Arrival

Calculating the delay at which sound arrives the circular microphone array

$$\tau_{(k,i)} = 2 \frac{R}{C} \sin\left(\frac{\theta_k - \theta_i}{2}\right) \sin\left(\frac{\theta_k - \theta_i}{2} + \theta_i - \varphi_s\right)$$

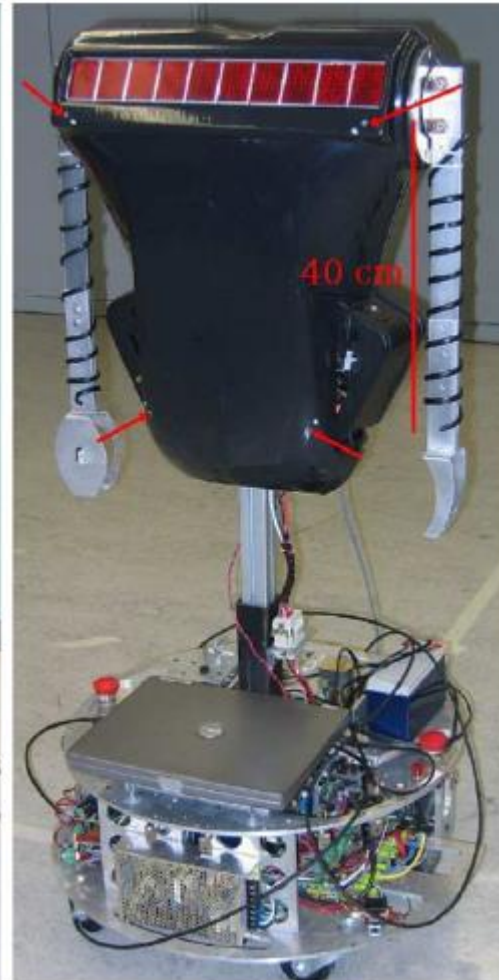
Approximating the angle by incrementing  $\varphi_s$  from  $0^\circ$  to  $360^\circ$  selecting the angle which reduces the difference between the analytical delay and that acquired through cross-correlation



[1]

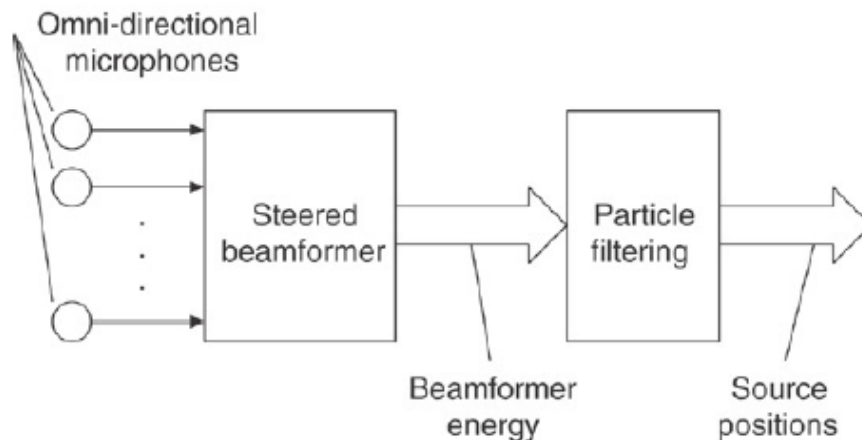
# Steered Beamforming

Robust localization and tracking of simultaneous moving sound sources using beamforming and particle filtering [2]



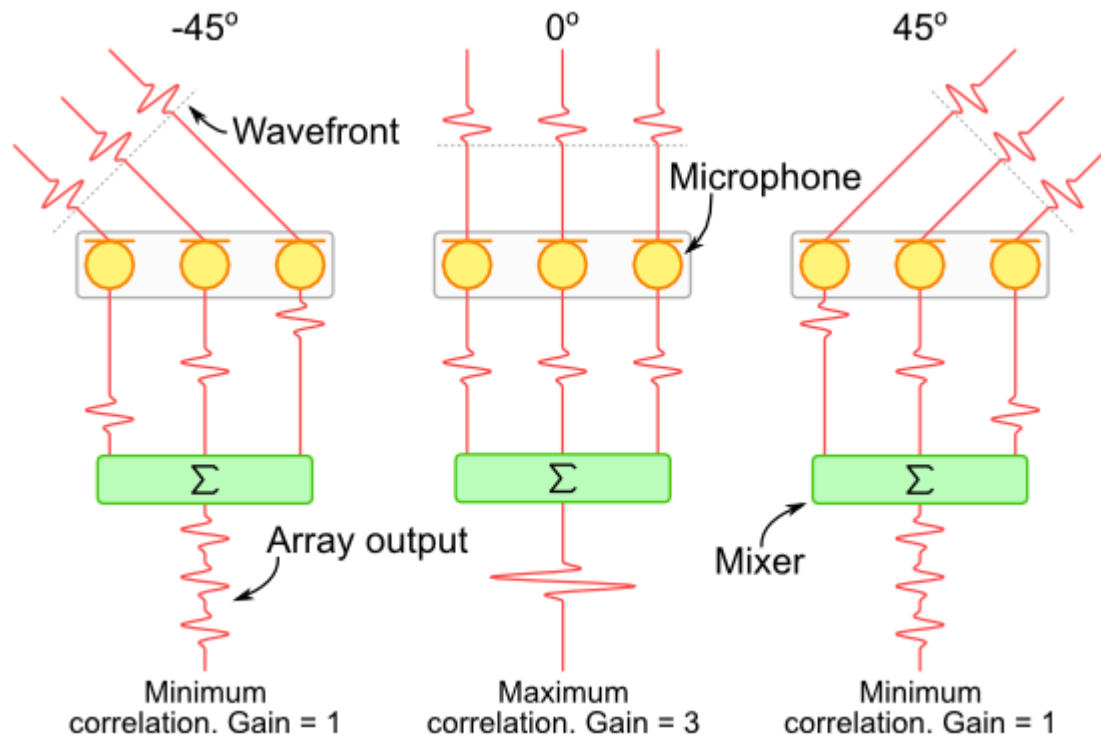
# Steered Beamforming

- Detect the sound from an array of omnidirectional microphones
- Steer the beam towards all possible angles
- Use particle filtering to predict the motion of the sound source
- Can detect angle and position !



[2]

# Steered Beamforming

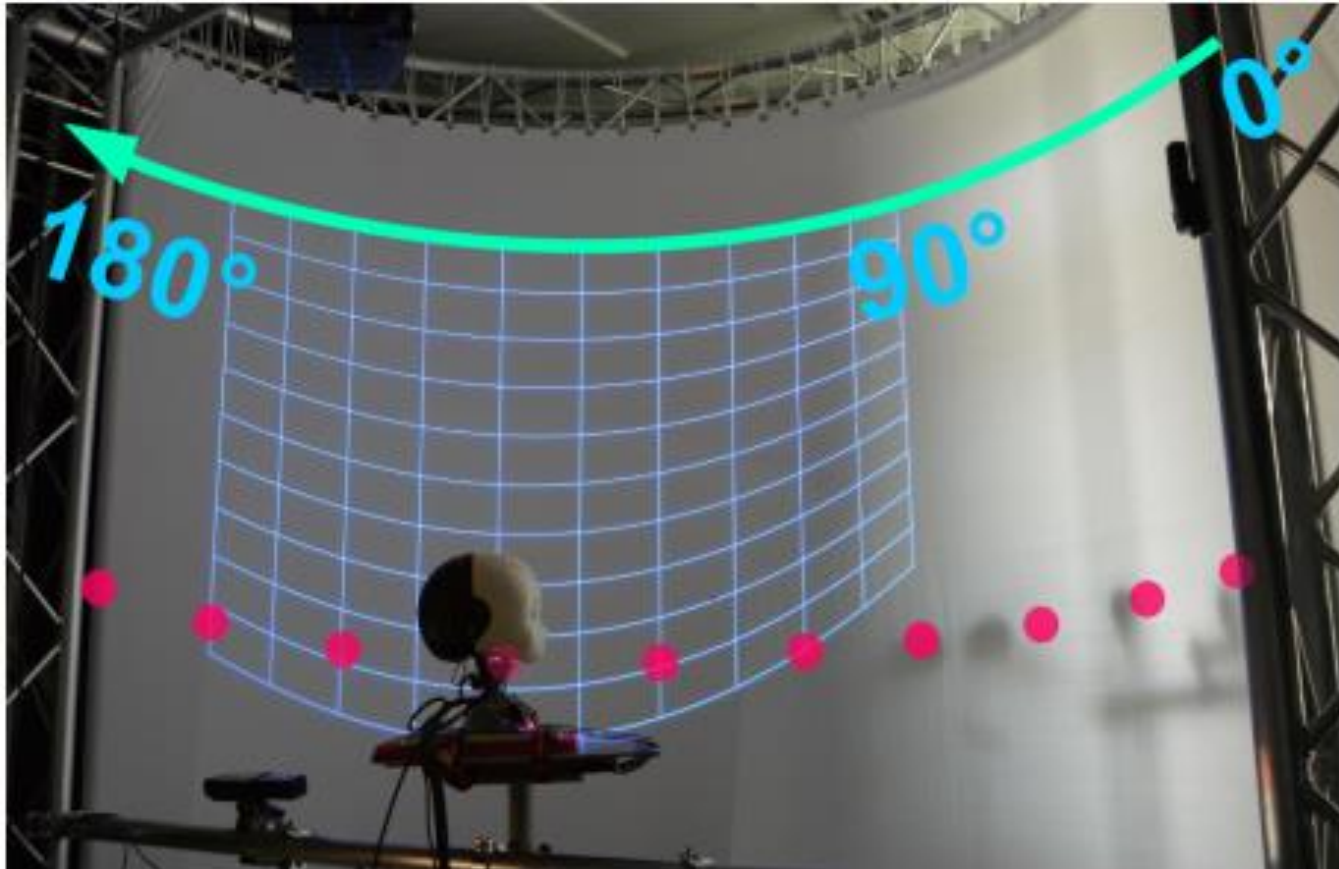


[5]

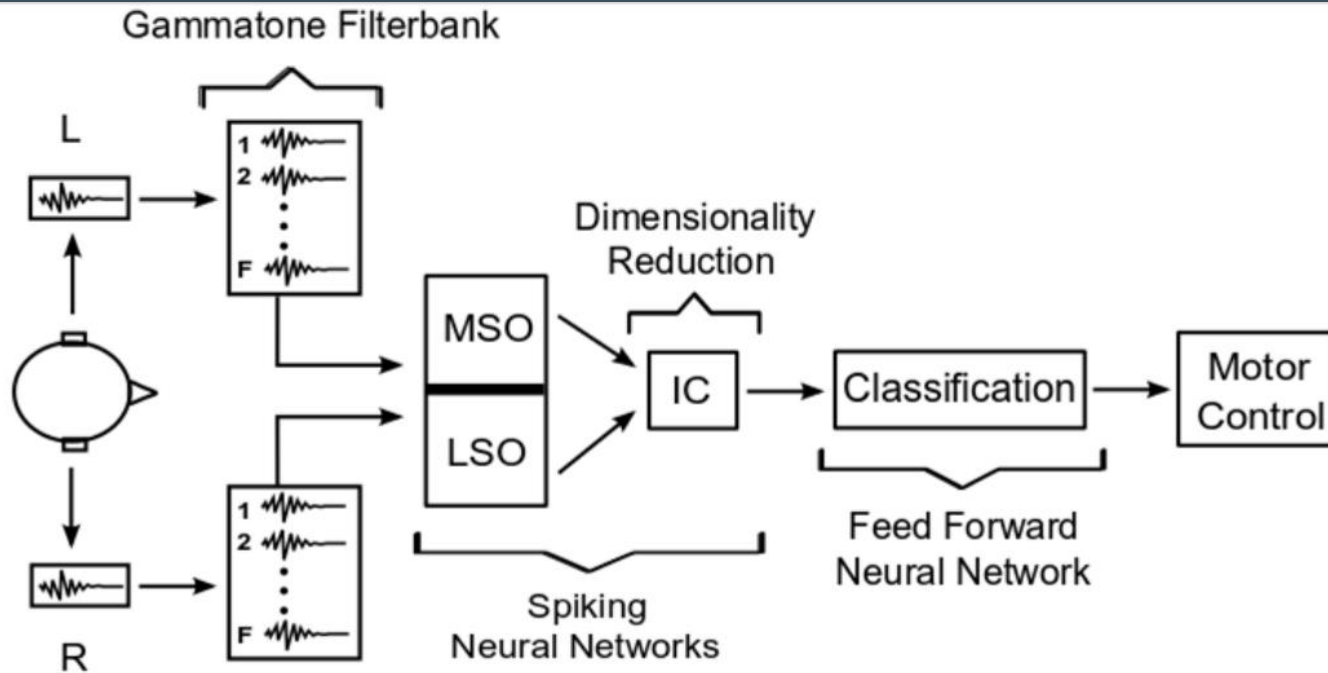
$$output = 20 \log_{10} \left( \frac{1}{N} \sum_{i=0}^{N-1} e^{\frac{j 2\pi f i l \sin(\theta)}{c}} \right)$$

# Bio-Inspired Sound Localization

## Neural and Statistical Processing of Spatial Cues for Sound Source Localisation [3]



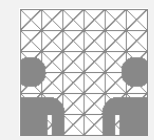
# Bio-Inspired Sound Localization



[3]

- Detect the direction of incoming sound
- Filter the sound signal (Gammatone FB)
- Detect ITD and ILD
- Reduce the dimensionality (Inferior Colliculus -> Naïve Bayes)
- Classify (FFNN)
- rotate the robot's head in the direction of the sound, aligning a single microphone with the sound source.





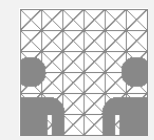
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# Comparison

	TDOA	Beamforming	Bio-Inspired SSL
Steps	Cross-Correlate and measure delay	Shift, Cross-Correlate, sum and measure power	Cross-Correlate, Minimize dimensionality, feed to network and predict
Speed	Fast	Moderate	Slow
Accuracy	Lowest	Moderate	Best
Resources	Low	High	High
Training	Not Required	Not Required	Required



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# Summary

- Mammals Localize sound through **binaural** and **monaural cues**
- **Interaural level difference (ILD)** is the measure of sound level/loudness across two inputs
- **Interaural time difference (ITD)** is the measure of sound level/loudness across two inputs
- **The Lateral Superior Olive (LSO)** : where ILD is measured in the brain
- **The Medial Superior Olive (MSO)** : where ITD is measured in the brain
- **Cross-Correlation** measures the delay between two signals
- Cross-Correlation is performed efficiently in the Frequency domain
- Quality effecting factors:
  - **Echo**
  - **Reverb**
  - **Noise**
  - **Doppler shift**



# Summary

- Computerized systems can measure the direction of sound by:
  - **Time difference of arrival or phase delay**
  - **Steered beamforming**
  - **Heuristic and statistical methods**
- Beamforming can detect more than a single sound source
- Sound can be detected by binaural or multi-microphone array systems (circular or aligned)



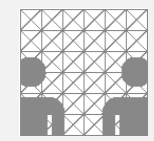
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- [1] M. Daoud, M. Al-Ashi, F. Abawi, and A. Khalifeh, “*In-house alert sounds detection and direction of arrival estimation to assist people with hearing difficulties,*” in IEEE/ACIS 14th International Conference on Computer and Information Science (ICIS), pp. 297–302, Nevada, US, June 2015.
- [2] J.-M. Valin, F. Michaud and J. Rouat, “*Robust localization and tracking of simultaneous moving sound sources using beamforming and particle filtering,*” Robotics Autonomous Syst. J. 55, 216– 228, 2007.
- [3] J. Davila-Chacon, S. Magg, J. Liu, and S. Wermter. “*Neural and statistical processing of spatial cues for sound source localization,*” in IEEE Intl. Conf. on Neural Networks (IJCNN-13), pp. 1–8, Dallas, US, 2013.



# References

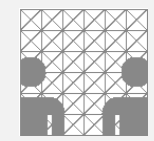
- [4] B. Grothe, M. Pecka, and D. McAlpine, “*Mechanisms of Sound Localization in Mammals*” in *Physiological Reviews* Published 1 July 2010 **Vol. 90 no. 3**, 983-1012  
<http://physrev.physiology.org/content/90/3/983>
  
- [5] A. Greensted, “Delay Sum Beamforming” in *The Lab Book Pages*, 2012  
<http://www.labbookpages.co.uk/audio/beamforming/delaySum.html>
  
- [6] J. Schnupp, E. Nelken, A. King, “The Jeffress Model – Animation” in *Auditory Neuroscience*  
<https://auditoryneuroscience.com/topics/jeffress-model-animation>
  
- [7] J. Schnupp, E. Nelken, A. King, “Binaural Cues” in *Auditory Neuroscience*  
<https://auditoryneuroscience.com/topics/binaural-cue-demos>
  
- [8] “Echo and Reverb animation” in *The Physics Classroom*  
<http://www.physicsclassroom.com/mmedia/waves/er.gif>
  
- [9] “Waves and Sound: The Doppler Effect” In *PHYSCLIPS* ,UNSW, School of Physics, Sydney  
<http://www.animations.physics.unsw.edu.au/jw/doppler.htm>



# Further Reading

- [10] B. Clénet and H. Romsdorfer, "*Circular microphone array based beamforming and source localization on reconfigurable hardware*". Diss. Master's thesis, Graz University of Technology, 2010.
- [11] J. Davila-Chacon, J. Twiefel, J. Liu, and S. Wermter. "*Improving Humanoid Robot Speech Recognition with Sound Source Localisation.*" International Conference on Artificial Neural Networks. Springer International Publishing, 2014.





Questions ?

*Thank you !*