

# Urban Search and Rescue Robots

17.11.2014

Vincent Leiß

# Structure

- Idea of Rescue Robots
- Development
- Pros and Cons of Rescue Robots
- Fukushima
  - ➔ Packbot
  - ➔ Requirements
  - ➔ Quince 1
  - ➔ Conclusion

# Rescue Robots?



# First attempt



*PackBot used in the World Trade Center*

# Current state of research



*Packbot used in Fukushima (2011)*

# Pros of Rescue Robots

---

- safe search
- general overview & data gathering
- perform small tasks
- Rescue Robots are quite small

# Disadvantages

---

- can't directly rescue survivors
- mobility problems
- many robots for different tasks
- non-autonomous (limited range)

# Fukushima

Improvements to the Rescue Robot Quince  
Toward Future Indoor Surveillance Missions in  
the Fukushima Daiichi Nuclear Power Plant

Tomoaki Yoshida, Keiji Nagatani, Eiji Koyanagi  
*Chiba Institute of Technology, Chiba, Japan*  
Satoshi Tadokoro and Takeshi Nishimura  
*Tohoku University, Sendai, Japan*

July 16, 2012  
Matsushima, Miyagi, Japan



# Fukushima-Introduction

- On March 11 2011 an earthquake and tsunami seriously damaged four reactors.
- Because of high radiation levels the assistance of robots was required.
- Japan itself didn't have a single rescue robot that was ready to be used in a nuclear power plant.

# Fukushima-Packbot

- The American Packbot robots managed to open an airlock gate to enter the building.



# Fukushima-Packbot

---

- Packbots were only able to gain access to the first floor
- Measurements confirmed high radiation dosage
- Another robot was needed to reach the higher floors and perform tasks

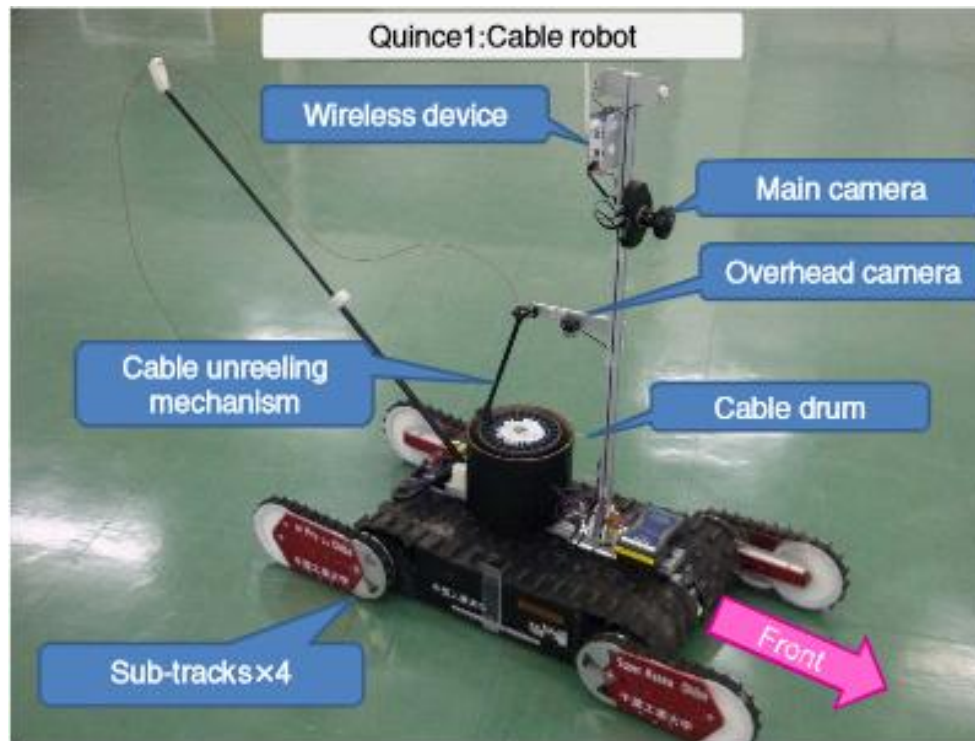
# Requirements

---

- Ability to climb stairs
- Cable communication system
- A good user interface
- Additional sensors
- Radiation protection
- Waterproof

# Fukushima-Quince 1

- Redesign of Quince



# Quince1- Control Panel



# Quince1- Missions(1)

## *Mission 1*

- task: install a water level measuring device
- problems: stair landings in the blueprints were larger than in reality
- result: failure

# Quince 1- Missions(2-5)

## *Missions 2-5*

- task: capture air dust samples and perform several measurements in different reactor units
- problems: overheated motor driver boards and rubble blocking staircases
- result: successful



# Quince 1- Missions(2-5)



# Quince1- Missions(6)

## *Mission 6*

- task: reach the 5th floor and observe the situation
- problems: on the way back the communication cable was jammed in the cable drum
- result: success, but the communication cable had to be cut off and Quince1 remains inside the reactor

# Fukushima-Conclusion

---

Rescue Robots had a big impact on getting control over the situation in Fukushima and showed how important further development is.

# Fukushima-Conclusion

