

# Behaviour Trees

## Seminar

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# Outline

- 1 Behaviour Trees
- 2 Extensions
- 3 vs HFSM
- 4 Handling Complexity in the Halo 2 AI

# Motivation

- Behaviour Trees are reusable
- => BTs scale well
- BTs are easily authored

# Behaviour Trees

- Directed tree
- Nodes are either *composites* or *leaves*
- Root is *ticked* every time step

# Behaviour Trees 2

- *Ticks* traverse down towards leaves
- Results traverse up towards the root
- Possible results: *Success, Failure, Running*

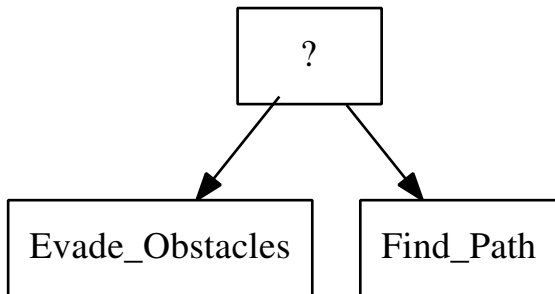
# Composites

- Selector
- Sequence
- Parallel
- Decorator

# Selector

- Behaves similar to logical OR
- Returns Success (Running) if any child returns Success
- Returns Failure if all children return Failure

## Selector 2

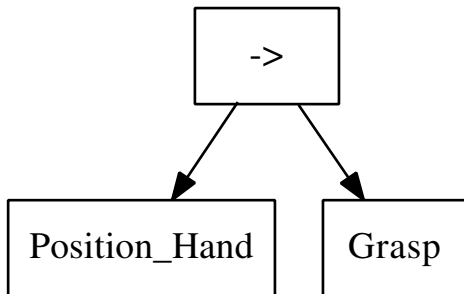




# Sequence

- Behaves similar to logical AND
- Returns Success if all children return Success
- Returns Failure (Running) otherwise

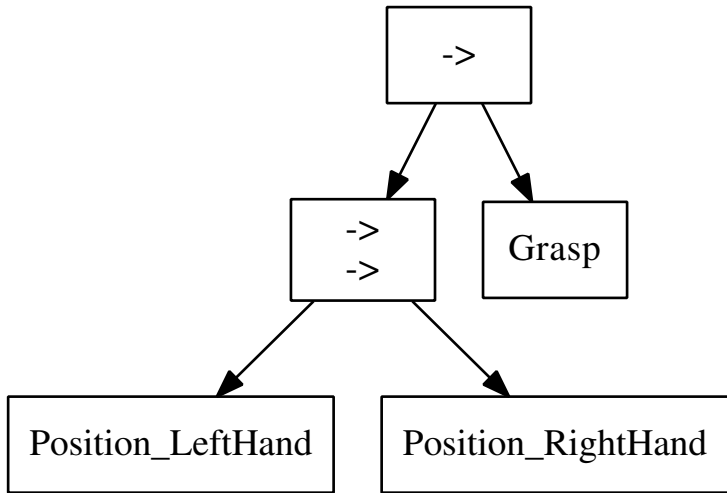
## Sequence 2



# Parallel

- Allows parallel execution of behaviours
- Returns Success if  $\geq S$  children succeed
- Returns Failure if  $\geq F$  children succeed
- Returns Running in any other case

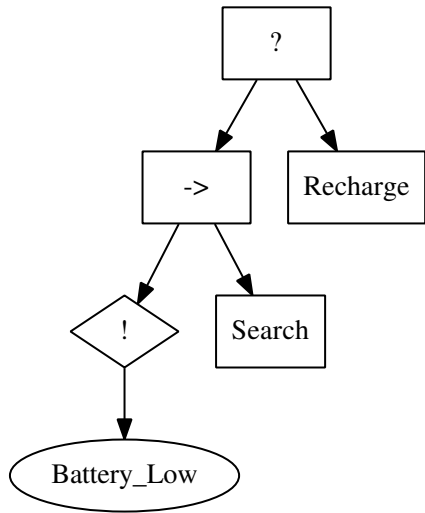
## Parallel 2



# Decorator

- Can only have **ONE** child
- Manipulate return value of child
- e.g. Inverter, Counter, Timer ...

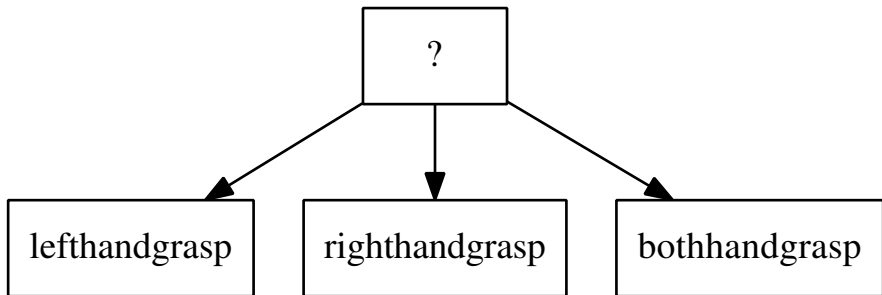
## Decorator 2



# Leaves

- Actions
- Conditions
- Leave can be another BT

# Behaviour Tree in Action



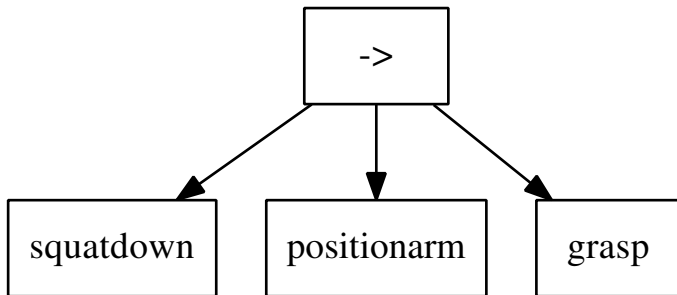


# Behaviour Tree in Action 2

First Experiment (0:00 - 1:15)

<http://www.youtube.com/watch?v=kEd2YxysBtI>

# Behaviour Tree in Action 3



# ~Decorator

- used to synchronize actions with other agents
- one agent broadcasts intended behaviour
- other agents can respond if interested

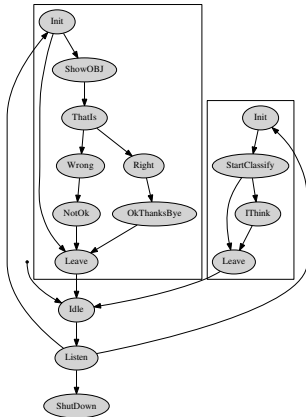
# Parametrized Behaviour Trees

- Subtrees can be parametrized
- SmartEvents contain parametrized Behaviour Tree
- Agents involved in SmartEvent will execute the BT once, then restart personal BT

# HFSM

- Large FSM can be hard to handle
- HFSM allows to use FSM as nodes...
- ... but still has the same problems

# HFSM Example



# Implicit vs Explicit State Transitions

- BT state transition similar to procedure call
- (H)FSM state transition similar to GoTo

# General Ideas

- Behaviour Trees are shared between characters
- Characters have a memory pool (e.g. Grenade Cooldown)
- Bitvectors represent characters world-knowledge and can lock behaviours



# Impulses & Stimuli

- Impulses reference other parts of BT
- Stimuli are inserted into BT when certain events happen
- Because of priority sorting stimuli only interrupt certain behaviours

# Orders

- Orders group Firing Positions
- Orders are assigned to Squads
- Trigger (e.g. Squadleader died) may assign new Orders

# Styles

- Styles can be assigned to Orders
- Styles can block certain behaviours (e.g. aggressive style prevents fleeing behaviour)

# The End

Thank you for your attention.

Any questions?



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In *Proceedings of the 2010 International Conference on Applications of Evolutionary Computation - Volume Part I, EvoApplicatons'10*, pages 100–110, Berlin, Heidelberg, 2010. Springer-Verlag.



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*Increasing Modularity of UAV Control Systems using Computer Game Behavior Trees.*

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